

Section 6.4

(4) Applying  $\mathcal{L}$  to both sides of the diff. eq., we have

$$\begin{aligned}\mathcal{L}\{y''\} + 4\mathcal{L}\{y\} &= \mathcal{L}\{\sin t\} + \mathcal{L}\{u_{\pi}(t) \sin(t-\pi)\} \\ &= \mathcal{L}\{\sin t\} + e^{-\pi s} \mathcal{L}\{\sin t\} \\ &= (1 + e^{-\pi s}) \mathcal{L}\{\sin t\} \\ &= \frac{1 + e^{-\pi s}}{s^2 + 1}\end{aligned}$$

$$\text{Then } \mathcal{L}\{y''\} = s^2 \mathcal{L}\{y\} - sy(0) - y'(0) = s^2 \mathcal{L}\{y\}$$

$$\text{So } s^2 \mathcal{L}\{y\} + 4\mathcal{L}\{y\} = \frac{1 + e^{-\pi s}}{s^2 + 1}$$

$$\Rightarrow (s^2 + 4) \mathcal{L}\{y\} = \frac{1 + e^{-\pi s}}{s^2 + 1}$$

$$\Rightarrow \mathcal{L}\{y\} = \frac{1 + e^{-\pi s}}{(s^2 + 4)(s^2 + 1)} \quad (*)$$

$$\text{Now } \frac{1}{(s^2 + 4)(s^2 + 1)} = \frac{As + B}{s^2 + 4} + \frac{Cs + D}{s^2 + 1}$$

$$\Rightarrow 1 = (As + B)(s^2 + 1) + (Cs + D)(s^2 + 4)$$

$$1 = As^3 + As + Bs^2 + B + Cs^3 + 4Cs + Ds^2 + 4D$$

$$1 = (A + C)s^3 + (B + D)s^2 + (A + 4C)s + (B + 4D)$$

So we need  $A + C = 0$ ,  $B + D = 0$ ,  $A + 4C = 0$ ,  $B + 4D = 1$

So  $A = -C$ , but on the other hand,  $A = -4C$ . So this means  $A = C = 0$ . Then  $B = -D$ , so  $B + 4D = -D + 4D = 3D = 1$

$\Rightarrow D = \frac{1}{3}$ , and  $B = -\frac{1}{3}$ . Hence

$$\frac{1}{(s^2+4)(s^2+1)} = \frac{-\frac{1}{3}}{s^2+4} + \frac{\frac{1}{3}}{s^2+1}$$

Now we write (\*) as

$$\mathcal{L}\{y\} = \frac{1}{(s^2+4)(s^2+1)} + e^{-\pi s} \cdot \frac{1}{(s^2+4)(s^2+1)} ; \text{ then since this}$$

$$\text{is } -\frac{1}{6} \cdot \frac{2}{s^2+4} + \frac{1}{3} \cdot \frac{1}{s^2+1}$$

$$= -\frac{1}{6} \mathcal{L}\{\sin 2t\} + \frac{1}{3} \mathcal{L}\{\sin t\}$$

$$= \mathcal{L}\left\{\frac{1}{3} \sin t - \frac{1}{6} \sin 2t\right\}, \text{ so}$$

$$\mathcal{L}\{y\} = \mathcal{L}\left\{\frac{1}{3} \sin t - \frac{1}{6} \sin 2t\right\} + \mathcal{L}\left\{u_{\pi}(t) \left[\frac{1}{3} \sin(t-\pi) - \frac{1}{6} \sin 2(t-\pi)\right]\right\}$$

$$\Rightarrow y(t) = \frac{1}{3} \sin t - \frac{1}{6} \sin 2t$$

$$+ u_{\pi}(t) \left[ \frac{1}{3} \sin(t-\pi) - \frac{1}{6} \sin(2t-2\pi) \right]$$

note this is the same as  $\sin 2t$ , and

this is just  $-\sin t$

$$\text{So } y(t) = \frac{1}{3} \sin t - \frac{1}{6} \sin 2t + u_{\pi}(t) \left[ -\frac{1}{3} \sin t - \frac{1}{6} \sin 2t \right]$$

$$\Rightarrow y(t) = \frac{1}{3} (\sin t) (1 - u_{\pi}(t)) - \frac{1}{6} (\sin 2t) (1 + u_{\pi}(t))$$

$$\textcircled{7} \mathcal{L}\{y''\} + \mathcal{L}\{y\} = \mathcal{L}\{u_{3\pi}\}$$

$$\Rightarrow s^2 \mathcal{L}\{y\} - sy(0) - y'(0) + \mathcal{L}\{y\} = \frac{e^{-3\pi s}}{s}$$

$$\Rightarrow (s^2 + 1) \mathcal{L}\{y\} - s = \frac{e^{-3\pi s}}{s}$$

$$\Rightarrow (s^2 + 1) \mathcal{L}\{y\} = \frac{e^{-3\pi s}}{s} + s$$

$$\Rightarrow \mathcal{L}\{y\} = \frac{e^{-3\pi s}}{s(s^2 + 1)} + \underbrace{\frac{s}{s^2 + 1}}_{\text{This is } \mathcal{L}\{\cos t\}}$$

Now  $\frac{1}{s(s^2 + 1)} = \frac{A}{s} + \frac{Bs + C}{s^2 + 1}$

$$\Rightarrow 1 = A(s^2 + 1) + (Bs + C)s$$

$$\Rightarrow 1 = As^2 + A + Bs^2 + Cs$$

$$\Rightarrow 1 = (A + B)s^2 + Cs + A$$

$$\text{So } A + B = 0 \Rightarrow A = -B$$

$$C = 0$$

$$\text{and } A = 1, \text{ so } B = -1$$

$$\Rightarrow \frac{1}{s(s^2 + 1)} = \frac{1}{s} - \frac{s}{s^2 + 1}$$

$$\text{So } \mathcal{L}\{y\} = e^{-3\pi s} \left( \frac{1}{s} - \frac{s}{s^2 + 1} \right) + \mathcal{L}\{\cos t\}$$

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$$= e^{-3\pi s} \mathcal{L}\{1 - \cos t\} + \mathcal{L}\{\cos t\}$$

$$\mathcal{L}\{1 - \cos t\} = \mathcal{L}\{u_{3\pi}(t)[1 - \cos(t - 3\pi)]\} + \mathcal{L}\{\cos t\}$$

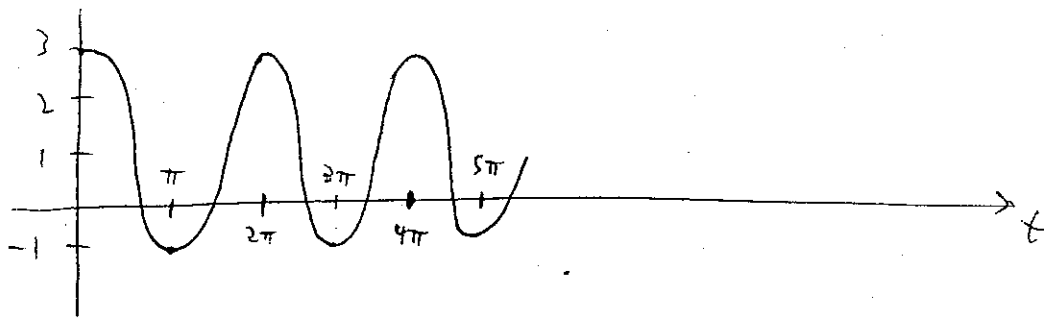
$$\text{So } y(t) = u_{3\pi}(t)[1 - \cos(t - 3\pi)] + \cos t$$

Now,  $\cos(t - 3\pi) = \cos(t - \pi) = -\cos t$ , so

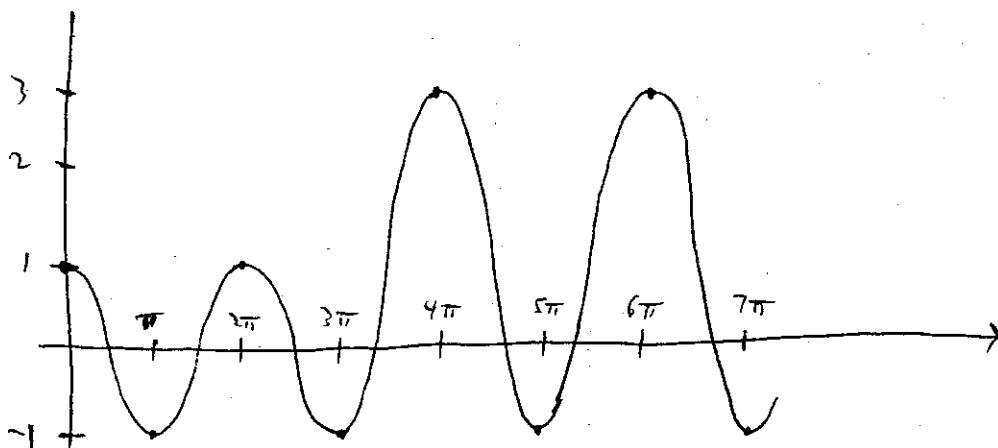
$$y(t) = u_{3\pi}(t)[1 + \cos t] + \cos t$$

$$= \begin{cases} \cos t & \text{for } 0 \leq t < 3\pi \\ 1 + 2\cos t & \text{for } t > 3\pi \end{cases}$$

Notice the function  $g(t) = 1 + 2\cos t$  looks like this:



So  $y(t)$  look-a like:



The external force which kicks in at  $t = 3\pi$  causes the amplitude to double. And if you think about it, the fact that the solution agrees with  $\cos t$  before that makes perfect sense, because the diff. eq.  $y'' + y = 0$  applies before  $t = 3\pi$ , and we know that solutions to this <sup>↑</sup> (a.k.a.  $y'' = -y$ ) are sines & cosines ... but look at the initial conditions:  $y(0) = 1$  and  $y'(0) = 0$ . So it's fairly obvious (well ... once you see it) that we get the cosine function at first.

Then for  $t \geq 3\pi$ , the governing diff. eq. becomes  $y'' + y = 1$ , and if you were to solve the IVP

~~$y'' + y = 0$   
 $y(0) = 1$   
 $y'(0) = 0$~~

$$y'' + y = 1$$

$$y(3\pi) = -1$$

$$y'(3\pi) = 0$$

you would find that the solution is  $y(t) = 1 + 2\cos t$

(10) We can write  $g(t) = (1 - u_\pi(t)) \sin t$ , but the problem with this is that ~~there~~ there is no formula handy for computing  $\mathcal{L}\{g\}$  because its form doesn't correspond to anything in the left column of Table 6.2.1. A little algebraic manipulation will help:

$$g(t) = \sin t - u_\pi(t) \sin t = \sin t - u_\pi(t) \cdot \sin[(t - \pi) + \pi]$$

So ... well, wait a minute, that's stupid; let's do this:

$$\sin(t - \pi) = -\sin t, \text{ so } g(t) = \sin t + u_{\pi}(t) \sin(t - \pi).$$

There we go. OK, now  $\mathcal{L}\{y''\} + \mathcal{L}\{y'\} + \frac{5}{4}\mathcal{L}\{y\} = \mathcal{L}\{g\}$

$$= \mathcal{L}\{\sin t\} + \mathcal{L}\{u_{\pi}(t) \sin(t - \pi)\} = \frac{1}{s^2 + 1} + \frac{e^{-\pi s}}{s^2 + 1} = \frac{1 + e^{-\pi s}}{s^2 + 1}$$

Then  $\mathcal{L}\{y''\} = s^2 \mathcal{L}\{y\} - sy(0) - y'(0) = s^2 \mathcal{L}\{y\}$

$$\mathcal{L}\{y'\} = s \mathcal{L}\{y\} - y(0) = s \mathcal{L}\{y\}$$

So we have  $(s^2 + s + \frac{5}{4}) \mathcal{L}\{y\} = \frac{1 + e^{-\pi s}}{s^2 + 1}$

$$\Rightarrow \mathcal{L}\{y\} = \frac{1 + e^{-\pi s}}{(s^2 + s + \frac{5}{4})(s^2 + 1)} \quad (\star)$$

Now this quadratic factor is irreducible

(i.e., not factor-able) because  $b^2 - 4(1)(\frac{5}{4}) = 1 - 5 < 0$

Now we consider  $\frac{1}{(s^2 + s + \frac{5}{4})(s^2 + 1)} = \frac{As + B}{s^2 + s + \frac{5}{4}} + \frac{Cs + D}{s^2 + 1}$

$$\Rightarrow 1 = (As + B)(s^2 + 1) + (Cs + D)(s^2 + s + \frac{5}{4})$$

$$1 = (A + C)s^3 + (B + C + D)s^2 + (A + \frac{5}{4}C + D)s + (B + \frac{5}{4}D)$$

Then we get the algebraic system

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$$\begin{array}{rcl} A & + C & = 0 \\ B & + C + D & = 0 \\ A & + \frac{5}{4}C + D & = 0 \\ B & + \frac{5}{4}D & = 1 \end{array}$$

Leaving out the tedious details, the solution is

$$A = \frac{16}{17}, B = \frac{12}{17}, C = -\frac{16}{17}, D = \frac{4}{17}$$

$$\text{So } \frac{1}{(s^2+s+\frac{5}{4})(s^2+1)} = \frac{4}{17} \left( \frac{4s+3}{s^2+s+\frac{5}{4}} + \frac{-4s+1}{s^2+1} \right) \quad (*)$$

$$\text{Now } s^2+s+\frac{5}{4} = (s^2+s+\frac{1}{4}) + 1 = (s+\frac{1}{2})^2 + 1$$

$$\text{Then } 4s+3 = 4(s+\frac{1}{2}) + 1, \text{ so } \frac{4s+3}{s^2+s+\frac{5}{4}}$$

$$= \frac{4(s+\frac{1}{2})}{(s+\frac{1}{2})^2+1} + \frac{1}{(s+\frac{1}{2})^2+1} = \mathcal{L} \{ 4e^{-\frac{1}{2}t} \cos t + e^{-\frac{1}{2}t} \sin t \}$$

$$\text{Next } \frac{-4s+1}{s^2+1} = \frac{-4s}{s^2+1} + \frac{1}{s^2+1} = \mathcal{L} \{ -4 \cos t + \sin t \}$$

$$\text{So } (*) \text{ is } \mathcal{L} \left\{ \frac{4}{17} \left( e^{-\frac{1}{2}t} [4 \cos t + \sin t] - 4 \cos t + \sin t \right) \right\}$$

and then from (\*) we get

$$y(t) = \frac{4}{17} \left( e^{-\frac{1}{2}t} [4 \cos t + \sin t] - 4 \cos t + \sin t \right)$$

$$+ u_{\pi}(t) \left[ \frac{4}{17} e^{-\frac{1}{2}(t-\pi)} [4 \cos(t-\pi) + \sin(t-\pi)] - 4 \cos(t-\pi) + \sin(t-\pi) \right]$$

Section 7.5

③ Writing  $x' = Ax$ , with  $A = \begin{bmatrix} 2 & -1 \\ 3 & -2 \end{bmatrix}$ , we find the eigenvalues of  $A$  by considering  $\det(A - rI) = \det \begin{bmatrix} 2-r & -1 \\ 3 & -2-r \end{bmatrix}$

$$= (2-r)(-2-r) + 3 = r^2 - 4 + 3 = r^2 - 1 = (r-1)(r+1) = 0$$

for  $r_1 = 1, r_2 = -1$ .

Considering  $A - r_1 I = A - I = \begin{bmatrix} 1 & -1 \\ 3 & -3 \end{bmatrix}$ , and solving

$$(A - I)\xi = 0, \text{ or } \left[ \begin{array}{cc|c} 1 & -1 & 0 \\ 3 & -3 & 0 \end{array} \right], \text{ we get } \left[ \begin{array}{cc|c} 1 & -1 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

$\Rightarrow \xi_1 - \xi_2 = 0$ , or  $\xi_1 = \xi_2$ . So  $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$ , for instance, is a suitable eigenvector.

$$\text{Then } A - r_2 I = A - (-1)I = A + I = \begin{bmatrix} 3 & -1 \\ 3 & -1 \end{bmatrix},$$

$$\text{and } (A + I)\xi = 0 \Rightarrow \left[ \begin{array}{cc|c} 3 & -1 & 0 \\ 3 & -1 & 0 \end{array} \right] \Rightarrow \left[ \begin{array}{cc|c} 3 & -1 & 0 \\ 0 & 0 & 0 \end{array} \right] \Rightarrow$$

$$3\xi_1 - \xi_2 = 0 \Rightarrow \begin{bmatrix} 1 \\ 3 \end{bmatrix} \text{ works as an eigenvector.}$$



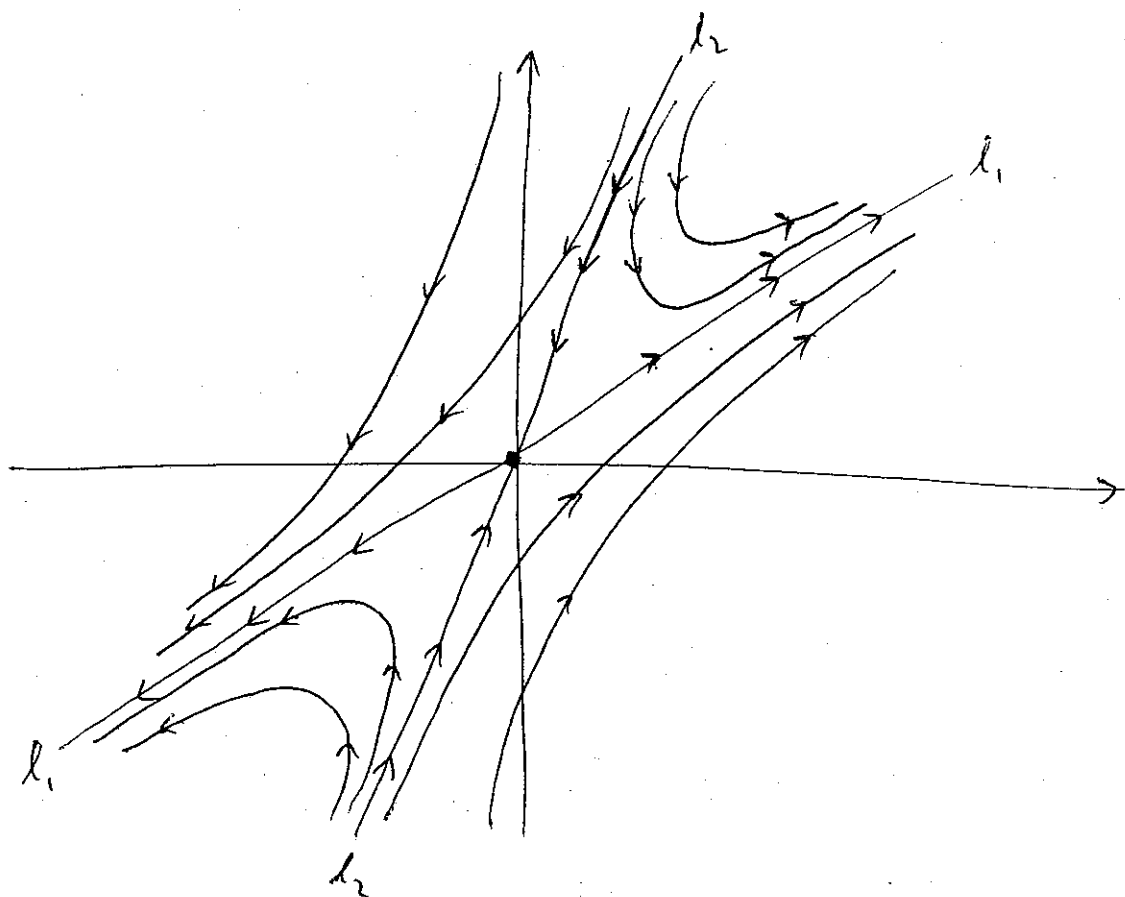
So the general solution to  $x' = Ax$  is

$$x = c_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} e^t + c_2 \begin{bmatrix} 1 \\ 3 \end{bmatrix} e^{-t}$$

Now this term  $\underbrace{\begin{bmatrix} 1 \\ 3 \end{bmatrix} e^{-t}}$  tends to 0 no matter the value of  $c_2$

Letting  $l_1 = \text{span} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$  and  $l_2 = \text{span} \begin{bmatrix} 1 \\ 3 \end{bmatrix}$ , we see that solution trajectories approach  $l_1$ , unless  $c_1 = 0$  (i.e., unless the solution starts out on  $l_2$ ), in which case the trajectory approaches  $(0,0)$ .

So trajectories look like this:



⑤ Write  $x' = Ax$  with  $A = \begin{bmatrix} -2 & 1 \\ 1 & -2 \end{bmatrix}$ , and  $\det(A - rI)$

$$= \det \begin{bmatrix} -2-r & 1 \\ 1 & -2-r \end{bmatrix} = (-2-r)^2 - 1 = (r+2)^2 - 1 =$$

$$r^2 + 4r + 4 - 1 = r^2 + 4r + 3 = (r+3)(r+1) = 0 \quad \text{for}$$

$r_1 = -3$  or  $r_2 = -1$ . (This tells us immediately that all solution trajectories approach the origin.)

Now  $A - r_1 I = A - (-3)I = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$ , so the system  $\begin{bmatrix} 1 & 1 & | & 0 \\ 1 & 1 & | & 0 \end{bmatrix}$ ,

or  $\begin{bmatrix} 1 & 1 & | & 0 \\ 0 & 0 & | & 0 \end{bmatrix}$ , yields  $\xi_1 + \xi_2 = 0$ , and  $\xi = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$  is a suitable

eigenvector.

Then  $A - r_2 I = A + I = \begin{bmatrix} -1 & 1 \\ 1 & -1 \end{bmatrix}$  yields the system  $\begin{bmatrix} -1 & 1 & | & 0 \\ 1 & -1 & | & 0 \end{bmatrix}$ ,

or  $\begin{bmatrix} -1 & 1 & | & 0 \\ 0 & 0 & | & 0 \end{bmatrix}$  with solution vectors  $\xi$  satisfying  $\xi_2 - \xi_1 = 0$ . So

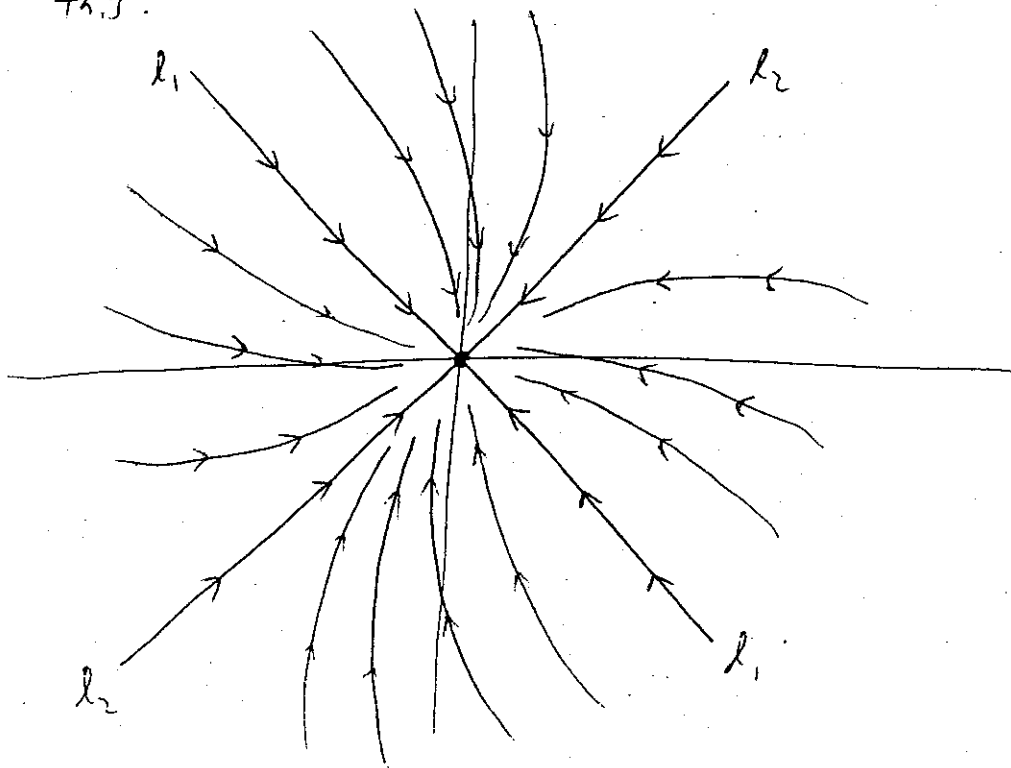
$\xi = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$  is a suitable eigenvector.

Solutions to  $x' = Ax$  are therefore of the form

$$x(t) = c_1 \begin{bmatrix} 1 \\ -1 \end{bmatrix} e^{-3t} + c_2 \begin{bmatrix} 1 \\ 1 \end{bmatrix} e^{-t}$$

Let  $l_1 = \text{span} \begin{bmatrix} 1 \\ -1 \end{bmatrix}$  and  $l_2 = \text{span} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ , and solution trajectories

look like this:



⑥ Here  $A = \begin{bmatrix} 5/4 & 3/4 \\ 3/4 & 5/4 \end{bmatrix}$ , so  $\det(A - rI) = \det \begin{bmatrix} \frac{5}{4} - r & \frac{3}{4} \\ \frac{3}{4} & \frac{5}{4} - r \end{bmatrix}$

$$= \left(r - \frac{5}{4}\right)^2 - \frac{9}{16} = r^2 - \frac{5}{2}r + \frac{25}{16} - \frac{9}{16} = r^2 - \frac{5}{2}r + 1$$

$$= 0 \iff 2r^2 - 5r + 2 = 0 \quad ; \quad \text{solutions are}$$

$$\textcircled{\ominus} \quad r = \frac{5 \pm \sqrt{25 - 16}}{4} = \frac{5 \pm 3}{4} \implies r_1 = 2, \quad r_2 = \frac{1}{2}$$

Now,  $A - r_1 I = \begin{bmatrix} -\frac{3}{4} & \frac{3}{4} \\ \frac{3}{4} & -\frac{3}{4} \end{bmatrix}$ , so  $(A - r_1 I)\xi = 0$  implies

$\xi_1 = \xi_2$ , so  $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$  works as an eigenvector.

Then  $A - r_2 I = A - \frac{1}{2} I = \begin{bmatrix} 3/4 & 3/4 \\ 3/4 & 3/4 \end{bmatrix}$ , and  $(A - \frac{1}{2} I)\xi = 0$

yields  $\xi_1 = -\xi_2$ . So  $\begin{bmatrix} -1 \\ 1 \end{bmatrix}$  is a suitable eigenvector corresponding

to  $r_2 = \frac{1}{2}$ .

So the general solution is  $x(t) = c_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} e^{2t} + c_2 \begin{bmatrix} -1 \\ 1 \end{bmatrix} e^{\frac{1}{2}t}$ ,

and unless the initial values are both 0, the individual solutions both grow, without bound, in magnitude. In fact, unless  $c_1 = 0$  the solution

trajectory always ends up in the first or third quadrant of the phase plane, moving roughly parallel to  $l_1 = \text{span} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ . Let  $l_2 =$

$\text{span} \begin{bmatrix} -1 \\ 1 \end{bmatrix}$ . Trajectories look like this:

