

The Laplacian in polar and spherical coordinates.

Polar coordinates.

The Laplacian is defined with respect to the canonical base of \mathbb{R}^N . Let us consider, for instance, the following problem

$$-\Delta u = 0, \quad \text{in } B_{\bar{r}}(0),$$

where $B_{\bar{r}}(0) := \{x \in \mathbb{R}^2 : |x| < \bar{r}\}$ is the ball of radius \bar{r} centered at the origin. Since the set $B_{\bar{r}}(0)$ has a spherical symmetry, it is more convenient to describe it with spherical coordinates (radius r and angle θ). That is, we describe points $(x, y) \in \mathbb{R}^2$ as

$$\begin{cases} x = r \cos \theta, \\ y = r \sin \theta. \end{cases}$$

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Let us consider the change of variable $P : (0, \infty) \times [0, 2\pi) \rightarrow \mathbb{R}^2 \setminus \{(0, 0)\}$ given by

$$P(r, \theta) := (r \cos \theta, r \sin \theta).$$

Notice that, for technical reasons of the change of variable, we are not considering the origin in the target space. This will not affect our computations. Now, define the function

$$v(r, \theta) := u(P(r, \theta)) = u(r \cos \theta, r \sin \theta).$$

We want to understand what equation v has to solve in the rectangle $[0, \bar{r}) \times [0, 2\pi)$ (that is, the set that describes the ball $B_{\bar{r}}(0)$), in order for the function u to solve the Laplace equation. In other terms, we want to understand how to write the Laplacian in polar coordinates. Namely, we would like to write

$$-\Delta u = -\partial_{xx}^2 u - \partial_{yy}^2 u,$$

as something involving only derivatives with respect to r and θ . For, let's reason as follows: we first write the first derivatives $\partial_x u$ and $\partial_y u$ in terms of $\partial_r v$ and $\partial_\theta v$. By applying the chain rule, we have that

$$\begin{cases} \partial_r v = \partial_x u \partial_r x + \partial_y u \partial_r y, \\ \partial_\theta v = \partial_x u \partial_\theta x + \partial_y u \partial_\theta y. \end{cases}$$

That is

$$\begin{cases} \partial_r v = \partial_x u \cos \theta + \partial_y u \sin \theta, \\ \partial_\theta v = -r \partial_x u \sin \theta + r \partial_y u \cos \theta. \end{cases}$$

That is, in a matrix form,

$$\begin{pmatrix} \partial_r v \\ \partial_\theta v \end{pmatrix} = \begin{pmatrix} \cos \theta & \sin \theta \\ -r \sin \theta & r \cos \theta \end{pmatrix} \begin{pmatrix} \partial_x u \\ \partial_y u \end{pmatrix} = DP(r, \theta) \begin{pmatrix} \partial_x u \\ \partial_y u \end{pmatrix},$$

where $DP(r, \theta)$ denotes the differential of the map P at the point (r, θ) . Since the above equation is true for every u (and the correspondent v), we can simply write it as an *equality between differential operators* as

$$\begin{pmatrix} \partial_r \\ \partial_\theta \end{pmatrix} = \begin{pmatrix} \cos \theta & \sin \theta \\ -r \sin \theta & r \cos \theta \end{pmatrix} \begin{pmatrix} \partial_x \\ \partial_y \end{pmatrix} = DP(r, \theta) \begin{pmatrix} \partial_x \\ \partial_y \end{pmatrix}.$$

What we want is $\partial_x u$ and $\partial_y u$ in terms of $\partial_r v$ and $\partial_\theta v$. so, we have to invert the above equality, that is

$$\begin{pmatrix} \partial_x \\ \partial_y \end{pmatrix} = (DP(r, \theta))^{-1} \begin{pmatrix} \partial_r \\ \partial_\theta \end{pmatrix},$$

where $(DP(r, \theta))^{-1}$ is the inverse of the matrix $DP(r, \theta)$, that is

$$(DP(r, \theta))^{-1} = \begin{pmatrix} \cos \theta & -\frac{\sin \theta}{r} \\ \sin \theta & \frac{\cos \theta}{r} \end{pmatrix}.$$

Thus, we get

$$\begin{pmatrix} \partial_x \\ \partial_y \end{pmatrix} = \begin{pmatrix} \cos \theta & -\frac{\sin \theta}{r} \\ \sin \theta & \frac{\cos \theta}{r} \end{pmatrix} \begin{pmatrix} \partial_r \\ \partial_\theta \end{pmatrix},$$

that is

$$\begin{cases} \partial_x = \cos \theta \partial_r - \frac{\sin \theta}{r} \partial_\theta, \\ \partial_y = \sin \theta \partial_r + \frac{\cos \theta}{r} \partial_\theta. \end{cases}$$

We now want to compute ∂_{xx}^2 . We have that

$$\begin{aligned} \partial_{xx}^2 &= \partial_x \partial_x = \left(\cos \theta \partial_r - \frac{\sin \theta}{r} \partial_\theta \right) \left(\cos \theta \partial_r - \frac{\sin \theta}{r} \partial_\theta \right) \\ &= \cos \theta \partial_r (\cos \theta \partial_r) + \cos \theta \partial_r \left(-\frac{\sin \theta}{r} \partial_\theta \right) - \frac{\sin \theta}{r} \partial_\theta (\cos \theta \partial_r) - \frac{\sin \theta}{r} \partial_\theta \left(-\frac{\sin \theta}{r} \partial_\theta \right) \\ &= \cos \theta (\partial_r \cos \theta) \partial_r + \cos^2 \theta \partial_r \partial_r + \cos \theta \partial_r \left(-\frac{\sin \theta}{r} \right) \partial_\theta - \frac{\cos \theta \sin \theta}{r} \partial_r \partial_\theta \\ &\quad - \frac{\sin \theta}{r} \partial_\theta (\cos \theta) \partial_r - \frac{\sin \theta \cos \theta}{r} \partial_\theta \partial_r - \frac{\sin \theta}{r} \partial_\theta \left(-\frac{\sin \theta}{r} \right) \partial_\theta + \frac{\sin^2 \theta}{r^2} \partial_\theta \partial_\theta \\ &= 0 + \cos^2 \theta \partial_{rr}^2 + \frac{1}{r^2} \cos \theta \sin \theta \partial_\theta - \frac{\cos \theta \sin \theta}{r} \partial_{r\theta}^2 \\ &\quad + \frac{\sin^2 \theta}{r} \partial_r - \frac{\cos \theta \sin \theta}{r} \partial_{r\theta}^2 + \frac{\sin \theta \cos \theta}{r^2} \partial_\theta + \frac{\sin^2 \theta}{r^2} \partial_{\theta\theta}^2. \end{aligned}$$

With similar computations, we get

$$\begin{aligned} \partial_{yy}^2 &= \partial_y \partial_y = \left(\sin \theta \partial_r + \frac{\cos \theta}{r} \partial_\theta \right) \left(\sin \theta \partial_r + \frac{\cos \theta}{r} \partial_\theta \right) \\ &= \sin^2 \theta \partial_{rr}^2 - \frac{1}{r^2} \cos \theta \sin \theta \partial_\theta + \frac{\cos \theta \sin \theta}{r} \partial_{r\theta}^2 \\ &\quad + \frac{\cos^2 \theta}{r} \partial_r + \frac{\cos \theta \sin \theta}{r} \partial_{r\theta}^2 - \frac{\sin \theta \cos \theta}{r^2} \partial_\theta + \frac{\cos^2 \theta}{r^2} \partial_{\theta\theta}^2. \end{aligned}$$

Thus, we can write

$$\Delta = \partial_{rr}^2 + \frac{1}{r} \partial_r + \frac{1}{r^2} \partial_{\theta\theta}.$$

The above is the expression of the Laplacian in polar coordinates. Notice that it is made by a *radial* component

$$\partial_{rr}^2 + \frac{1}{r} \partial_r,$$

and by an *angular* one

$$\partial_{\theta\theta}.$$

In our example, this means that, u solves the Laplace equation in the ball $B_r(0)$ if and only if v solves the equation

$$\partial_{rr}^2 v + \frac{1}{r} \partial_r v + \frac{1}{r^2} \partial_{\theta\theta} v = 0,$$

in the rectangle $[0, r) \times [0, 2\pi)$. Even if at a first glance this does not seem like a good simplification of the problem we will see that it is possible to solve the equation for v .

Spherical coordinates.

We would like to perform the same computation in dimension $N = 3$ with the spherical

coordinates, that is, when we describe a point $(x, y, z) \in \mathbb{R}^3$ as

$$\begin{cases} x = r \sin \varphi \cos \theta, \\ y = r \sin \varphi \sin \theta, \\ z = r \cos \varphi. \end{cases}$$

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In order to do so, we will take advantage of the previous computations and we will add an additional variable (that we will get rid in the end). We call

$$s := \sqrt{x^2 + y^2} = r \sin \varphi,$$

and we write the above system as

$$\begin{cases} x = s \cos \theta, \\ y = s \sin \theta, \\ z = r \cos \varphi. \end{cases}$$

By considering the planes xy and, for θ fixed, the plane sz , by the previous computations, we have that

$$\begin{aligned} \partial_{xx}^2 + \partial_{yy}^2 &= \partial_{ss}^2 + \frac{1}{s} \partial_s + \frac{1}{s^2} \partial_{\theta\theta}, \\ \partial_{ss}^2 + \partial_{zz}^2 &= \partial_{rr}^2 + \frac{1}{r} \partial_r + \frac{1}{r^2} \partial_{\varphi\varphi}. \end{aligned}$$

Then

$$\Delta = \partial_{xx}^2 + \partial_{yy}^2 + \partial_{zz}^2 = \partial_{rr}^2 + \frac{1}{r} \partial_r + \frac{1}{r^2} \partial_{\varphi\varphi} + \frac{1}{s} \partial_s + \frac{1}{s^2} \partial_{\theta\theta}. \quad (1)$$

We now just have to rewrite the last two terms with respect to derivatives in r, θ, φ . For, notice that, by the definition of s ,

$$\frac{1}{s^2} \partial_{\theta\theta} = \frac{r^2 \sin^2 \varphi}{\partial_{\theta\theta}^2}.$$

Moreover, by the chain rule, we have that

$$\partial_s = \partial_r \frac{\partial r}{\partial s} + \partial_\varphi \frac{\partial \varphi}{\partial s} + \partial_\theta \frac{\partial \theta}{\partial s}.$$

We have that

$$\frac{\partial \theta}{\partial s} = 0,$$

since the variable θ does not depend on s , while

$$\frac{\partial r}{\partial s} = \frac{\partial}{\partial s} \sqrt{s^2 + z^2} = \frac{s}{r}.$$

Finally, in order to compute $\frac{\partial \varphi}{\partial s}$, we reason as follows: by definition

$$s = r \sin \varphi.$$

By differentiating both terms with respect to s , we get

$$1 = \frac{r}{s} \sin \varphi + r \cos \varphi \frac{\partial \varphi}{\partial s}.$$

Thus,

$$\frac{\partial \varphi}{\partial s} = \frac{r - s \sin \varphi}{r^2 \cos \varphi} = \frac{\cos \varphi}{r}.$$

By plugging in these expression in (1), we finally get

$$\boxed{\Delta = \partial_{rr}^2 + \frac{2}{r} \partial_r + \frac{1}{r^2} \left[\partial_{\varphi\varphi}^2 + \frac{\cos \varphi}{\sin \varphi} \partial_\varphi + \frac{1}{\sin^2 \varphi} \partial_{\theta\theta}^2 \right]}.$$

Again, also here we notice that the radial and the angular part are separated. This last one, is called the **Laplace-Beltrami operator**, and functions w defined on the sphere (the boundary of the ball!) for which

$$\partial_{\varphi\varphi}^2 w + \frac{\cos \varphi}{\sin \varphi} \partial_{\varphi} w + \frac{1}{\sin^2 \varphi} \partial_{\theta\theta}^2 w = 0,$$

are called **spherical harmonics**.