Department of Mathematical Sciences
CARNEGIE MELLON UNIVERSITY

## OPERATIONS RESEARCH II 21-393

Homework 2: Due Monday September 24.

Q1 Solve the infinite horizon problem for the given matrix of costs. Assume that $\alpha=1 / 2$.

$$
\left[\begin{array}{llll}
5 & 4 & 1 & 8 \\
2 & 1 & 5 & 6 \\
3 & 1 & 5 & 4 \\
4 & 3 & 6 & 1
\end{array}\right]
$$

Begin with the policy

$$
\pi(1)=4, \pi(2)=4, \pi(3)=3, \pi(4)=4
$$

## Solution:

$$
\pi(1)=4, \pi(2)=4, \pi(3)=3, \pi(4)=4 .
$$

Evaluate policy.

$$
\begin{aligned}
& y_{1}=1+\frac{y_{4}}{2}=9 \\
& y_{2}=1+\frac{y_{4}}{2}=7 \\
& y_{3}=1+\frac{y_{3}}{2}=10 \\
& y_{4}=1+\frac{y_{4}}{2}=2
\end{aligned}
$$

We must now check for optimality:

$$
\begin{array}{cccc}
5+9 / 2 & 2+9 / 2 & 3+9 / 2 & 4+9 / 2 \\
4+7 / 2 & 1+7 / 2 * & 1+7 / 2 * & 3+7 / 2 \\
1+10 / 2 * & 5+10 / 2 & 5+10 / 2 & 6+10 / 2 \\
8+2 / 2 & 6+2 / 2 & 4+2 / 2 & 1+2 / 2 *
\end{array}
$$

New policy is

$$
\pi(1)=3, \pi(2)=2, \pi(3)=2, \pi(4)=4 .
$$

$$
\begin{aligned}
& y_{1}=1+\frac{y_{3}}{2}=2 . \\
& y_{2}=1+\frac{y_{2}}{2}=2 . \\
& y_{3}=1+\frac{y_{2}}{2}=2 . \\
& y_{4}=1+\frac{y_{4}}{2}=2 .
\end{aligned}
$$

We must now check for optimality:

$$
\begin{array}{cccc}
5+2 / 2 & 2+2 / 2 & 3+2 / 2 & 4+2 / 2 \\
4+2 / 2 & 1+2 / 2 * & 1+2 / 2 * & 3+2 / 2 \\
1+2 / 2 * & 5+2 / 2 & 5+2 / 2 & 6+2 / 2 \\
8+2 / 2 & 6+2 / 2 & 4+2 / 2 & 1+2 / 2 *
\end{array}
$$

So, new policy is optimal.
Q2 Solve the following problem by a cutting plane algorithm:

$$
\begin{aligned}
& \begin{array}{lll}
\operatorname{minimise} & 4 x_{1} & +5 x_{2}+3 x_{3} \\
\text { subject to } \\
& 2 x_{1} & +x_{2}-x_{3} \geq 2 \\
& x_{1}+4 x_{2}+x_{3} \geq 13 \\
x_{1}, x_{2}, x_{3} & \geq 0 \text { and integer. }
\end{array} .
\end{aligned}
$$

## Solution:

Initial tableau

| $x_{1}$ | $x_{2}$ | $x_{3}$ | $x_{4}$ | $x_{5}$ | R.H.S |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :--- |
| -4 | -5 | -3 | 0 | 0 | 0 | z |
| -2 | -1 | 1 | 1 | 0 | -2 | $x_{4}$ |
| -1 | -4 | -1 | 0 | 1 | -13 | $x_{5} \leftarrow$ |
|  | $\uparrow$ |  |  |  |  |  |
| $x_{1}$ | $x_{2}$ | $x_{3}$ | $x_{4}$ | $x_{5}$ | R.H.S |  |
| $\frac{-11}{4}$ | 0 | $\frac{-7}{4}$ | 0 | $\frac{-5}{4}$ | $\frac{65}{4}$ | z |
| $\frac{-7}{4}$ | 0 | $\frac{5}{4}$ | 1 | $\frac{-1}{4}$ | $\frac{5}{4}$ | $x_{4}$ |
| $\frac{1}{4}$ | 1 | $\frac{1}{4}$ | 0 | $\frac{-1}{4}$ | $\frac{13}{4}$ | $x_{2}$ |

Primal feasible, but the solution is not integral.

We add a cut which eliminates the current optimal solution.

$$
\frac{1}{4} x_{1}+\frac{1}{4} x_{3}+\frac{3}{4} x_{5}-y_{1}=\frac{1}{4}
$$

| $x_{1}$ | $x_{2}$ | $x_{3}$ | $x_{4}$ | $x_{5}$ | $y_{1}$ | R.H.S |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :--- |
| $\frac{-11}{4}$ | 0 | $\frac{-7}{4}$ | 0 | $\frac{-5}{4}$ | 0 | $\frac{65}{4}$ | Z |
| $\frac{-7}{4}$ | 0 | $\frac{5}{4}$ | 1 | $\frac{-1}{4}$ | 0 | $\frac{5}{4}$ | $x_{4}$ |
| $\frac{1}{4}$ | 1 | $\frac{1}{4}$ | 0 | $\frac{-1}{4}$ | 0 | $\frac{13}{4}$ | $x_{2}$ |
| $\frac{-11}{4}$ | 0 | $\frac{-1}{4}$ | 0 | $\frac{-3}{4}$ | +1 | $\frac{-1}{4}$ | $y_{1} \leftarrow$ |
|  |  |  |  | $\uparrow$ |  |  |  |

We do a dual simplex pivot to obtain

| $x_{1}$ | $x_{2}$ | $x_{3}$ | $x_{4}$ | $x_{5}$ | $y_{1}$ | R.H.S |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :--- |
| $\frac{-7}{3}$ | 0 | $\frac{-4}{3}$ | 0 | $\frac{-5}{3}$ | 0 | $\frac{50}{3}$ | Z |
| $\frac{-5}{3}$ | 0 | $\frac{4}{3}$ | 1 | 0 | $\frac{-1}{3}$ | $\frac{4}{3}$ | $x_{4}$ |
| $\frac{1}{3}$ | 1 | $\frac{1}{3}$ | 0 | 0 | $\frac{-1}{3}$ | $\frac{10}{3}$ | $x_{2}$ |
| $\frac{1}{3}$ | 0 | $\frac{1}{3}$ | 0 | 1 | $\frac{-4}{3}$ | $\frac{1}{3}$ | $x_{5}$ |

The solution is primal feasible and so optimal but still not integer.
We add a cut which eliminates the current optimal solution.

$$
\frac{-1}{3} x_{1}-\frac{1}{3} x_{3}+y_{2}=\frac{1}{3}
$$

We obtain tableau

| $x_{1}$ | $x_{2}$ | $x_{3}$ | $x_{4}$ | $x_{5}$ | $y_{2}$ | R.H.S |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :--- |
| $\frac{-7}{3}$ | 0 | $\frac{-4}{3}$ | 0 | 0 | 0 | $\frac{50}{3}$ | z |
| $\frac{-5}{3}$ | 0 | $\frac{4}{3}$ | 1 | 0 | 0 | $\frac{4}{3}$ | $x_{4}$ |
| $\frac{1}{3}$ | 1 | $\frac{1}{3}$ | 0 | 0 | 0 | $\frac{10}{3}$ | $x_{2}$ |
| $\frac{1}{3}$ | 0 | $\frac{1}{3}$ | 0 | 1 | 0 | $\frac{1}{3}$ | $x_{5}$ |
| $\frac{-1}{3}$ | 0 | $\frac{-1}{3}$ | 0 | 0 | 1 | $\frac{1}{3}$ | $y_{2} \leftarrow$ |
|  |  | $\uparrow$ |  |  |  |  |  |

We do a dual simplex pivot to obtain

| $x_{1}$ | $x_{2}$ | $x_{3}$ | $x_{4}$ | $x_{5}$ | $y_{2}$ | R.H.S |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| -1 | 0 | 0 | 0 | 0 | -4 | 18 | z |
| -3 | 0 | 0 | 1 | 0 | 4 | 0 | $x_{4}$ |
| 0 | 1 | 0 | 0 | 0 | 1 | 3 | $x_{2}$ |
| 0 | 0 | 0 | 0 | 1 | 1 | 0 | $x_{5}$ |
| 1 | 0 | 1 | 0 | 0 | -3 | 1 | $x_{3}$ |

Which is optimal integral.
Q3 An assembly line consists of a sequence of locations called work stations. The manufacture of a certain object requires $m$ separate jobs to be undertaken with job $i$ requiring $t_{i}$ minutes. The jobs are to be allocated to work stations so that each station completes a set of jobs and then passes the object onto the next station on the line and waits to receive the next object from the previous station on the line. The combined time of all jobs assigned to any station must not exceed $T$ the cycle time. Also there are a number of precedence relations between jobs indicated by the digraph $D=(V, A)$ where $(i, j) \in A$ if job $i$ must precede job $j$. The problem is to open as few work stations as possible consistent with the cycle time. Formulate this as an integer programming problem.
(Hint: let $x_{i, j}=1$ iff job $j$ is done on station $i$ and $y_{i}=1$ if there is at least one job assigned to station $i$.)

## Solution:

$$
\begin{aligned}
\min \sum_{i=1}^{m} y_{i} & \\
\text { subject to } & \\
x_{i j} & \leq y_{i} \quad \forall i, j \in\{1, \ldots, m\} \\
\sum_{j=1}^{m} x_{i j} t_{j} & \leq T \quad \forall i \in\{1,2, \ldots, m\} \\
\sum_{i=1}^{m} x_{i j} & =1 \quad \forall j \in\{1,2, \ldots, m\} \\
\sum_{i=1}^{k} x_{i j_{2}} & \leq \sum_{i=1}^{k} x_{i j_{1}} \quad \forall\left(j_{1}, j_{2}\right) \in A, k=1,2, \ldots, m \\
x_{i j} & \in\{0,1\} \forall i, j \in\{1, \ldots, m\} \\
y_{i} & \in\{0,1\} \forall i \in\{1, \ldots, m\}
\end{aligned}
$$

The first constraint ensures that if any job is done at station $i$, the variable $y_{i}$ is 1 .

The second constraint ensures that each station satisfies the cycle time $T$.

The third constraint ensures that each job is scheduled on some machine. The last constraint ensures that $j_{1}$ is done before job $j_{2}$ if there is a precedence constraint between them.

