

Energy with Weight for S^2 -Valued Maps with Prescribed Singularities

Vincent Millot

LABORATOIRE J.L. LIONS, UNIVERSITÉ PIERRE ET MARIE CURIE, B.C. 187

4 PLACE JUSSIEU, 75252 PARIS CEDEX 05, FRANCE

E-mail adress: millot@ann.jussieu.fr

Abstract

We generalize a result of H. Brezis, J.M. Coron and E. Lieb concerning the infimum of the Dirichlet energy over classes of S^2 -valued maps with prescribed singularities to an energy with measurable weight and we prove some geometric properties of such quantity. We also give some stability and approximation results.

1 Introduction and Main Results

Let Ω be a smooth bounded and connected open set of \mathbb{R}^3 or $\Omega = \mathbb{R}^3$ and let $w : \Omega \rightarrow \mathbb{R}$ be a measurable function such that

$$0 < \lambda \leq w \leq \Lambda \quad \text{a.e. in } \Omega \quad (1.1)$$

for some constant λ and Λ . We consider N distinct points a_1, \dots, a_N in Ω and we define the following class of S^2 -valued maps

$$\mathcal{E} = \left\{ u \in C_{\text{loc}}^1(\overline{\Omega} \setminus \cup_i \{a_i\}, S^2), u = \text{const on } \partial\Omega, \int_{\Omega} |\nabla u(x)|^2 dx < +\infty, \deg(u, a_i) = d_i \quad \text{for } i = 1, \dots, N \right\}$$

(without boundary condition if $\Omega = \mathbb{R}^3$) where the d_i 's are given in $\mathbb{Z} \setminus \{0\}$ and such that $\sum d_i = 0$ (which is a necessary and sufficient condition for \mathcal{E} to be non-empty, see [9]). Our goal is to establish a formula for

$$E_w((a_i, d_i)_{i=1}^N) = \inf_{u \in \mathcal{E}} \int_{\Omega} |\nabla u(x)|^2 w(x) dx. \quad (1.2)$$

In [9], H. Brezis, J.M. Coron and E. Lieb have proved that for $w \equiv 1$ this quantity is equal to $8\pi L$ where L is the *length of a minimal connection* associated to the configuration $(a_i, d_i)_{i=1}^N$ and the Euclidean geodesic distance d_Ω on $\bar{\Omega}$ (see also [1, 6, 7, 17]). The first motivation for studying such a problem comes from the theory of liquid crystals (see [14, 15]). Later F. Bethuel, H. Brezis and J.M. Coron have shown that the notion of minimal connection is very useful when dealing with questions of approximation of S^2 -maps by smooth S^2 -maps in the strong H^1 -topology (see [2, 3]). We also refer to the results of J. Bourgain, H. Brezis, P. Mironescu [4] and H. Brezis, P. Mironescu, A.C. Ponce [10] for some similar problems involving S^1 -valued maps. In the *dipole case*, namely when we have two prescribed points P and N of degree $+1$ and -1 respectively, the value of L is equal to $d_\Omega(P, N)$. When w is continuous, we prove that $E_w(P, N) = 8\pi\delta_w(P, N)$ where δ_w denotes the Riemannian distance on $\bar{\Omega}$ defined by

$$\delta_w(P, N) = \text{Inf} \int_0^1 w(\gamma(t)) |\dot{\gamma}(t)| dt, \quad (1.3)$$

where the infimum is taken over all curves $\gamma \in \text{Lip}_{P,N}([0, 1], \bar{\Omega})$. Here $\text{Lip}_{P,N}([0, 1], \bar{\Omega})$ denotes the set of all Lipschitz maps γ from $[0, 1]$ with values into $\bar{\Omega}$ such that $\gamma(0) = P$ and $\gamma(1) = N$. For a general measurable function w , we prove that $E_w(P, N)$ induces a geodesic distance on $\bar{\Omega}$ (in the sense defined in Section 2.1). We call the attention of the reader to the fact that, in the measurable case, there is no way to define a distance by a formula like (1.3) since w is not well defined on curves which are sets of null Lebesgue measure. To overcome this difficulty, we construct a kind of “length structure” in which the general idea is to thicken the curves. We proceed as follows. For two points x and y in Ω , we consider the class $\mathcal{P}(x, y)$ of all finite collections of segments $\mathcal{F} = ([\alpha_k, \beta_k])_{k=1}^{n(\mathcal{F})}$ such that $\beta_k = \alpha_{k+1}$, $\alpha_1 = x$, $\beta_{n(\mathcal{F})} = y$ and $[\alpha_k, \beta_k] \subset \Omega$. We define “the length” of an element $\mathcal{F} \in \mathcal{P}(x, y)$ by

$$\ell_w(\mathcal{F}) = \sum_{k=1}^{n(\mathcal{F})} \liminf_{\varepsilon \rightarrow 0^+} \frac{1}{\pi\varepsilon^2} \int_{\Xi([\alpha_k, \beta_k], \varepsilon) \cap \Omega} w(\xi) d\xi.$$

where $\Xi([\alpha_k, \beta_k], \varepsilon) = \{ \xi \in \mathbb{R}^3, \text{dist}(\xi, [\alpha_k, \beta_k]) \leq \varepsilon \}$ and then we consider the function $d_w : \Omega \times \Omega \rightarrow \mathbb{R}_+$ defined by

$$d_w(x, y) = \text{Inf}_{\mathcal{F} \in \mathcal{P}(x, y)} \ell_w(\mathcal{F}).$$

In Section 2, we extend d_w to $\bar{\Omega} \times \bar{\Omega}$ and we prove the metric and geodesic character of d_w . We also show that d_w agrees with δ_w whenever w is continuous. In the third section, we give the proof of the following result.

Theorem 1.1. *We have*

$$E_w((a_i, d_i)_{i=1}^N) = 8\pi L_w$$

where L_w is the length of a minimal connection associated to the configuration $(a_i, d_i)_{i=1}^N$ and the distance d_w on $\bar{\Omega}$.

The geodesic character of the distance d_w implies that d_w coincides with the distance induced by the length functional associated to the Finsler metric φ_w obtained by differentiation of d_w (cf. Section 2.2). More precisely, for every P and N in $\bar{\Omega}$, we prove that

$$d_w(P, N) = \text{Min} \left\{ \int_0^1 \varphi_w(\gamma(t), \dot{\gamma}(t)) dt, \gamma \in \text{Lip}_{P,N}([0, 1], \bar{\Omega}) \right\}. \quad (1.4)$$

Formula (1.4) shows that, for a non-smooth w , the quantity $E_w((a_i, d_i)_{i=1}^N)$ is still given in terms of shortest paths between the a_i 's but the metric we compute the lengths with might be non-isotropic (a metric φ is said to be isotropic if $\varphi(x, \nu) = p(x)|\nu|$ for some positive function p).

We recall that the length L_w of a minimal connection is computed as follows (see [9]). We relabel the points a_i , taking into account their multiplicity $|d_i|$, as two lists of positive and negative points say (p_1, \dots, p_K) and (n_1, \dots, n_K) (note that this two lists have the same number of elements since $\sum d_i = 0$). Then we have

$$L_w = \text{Min}_{\sigma \in \mathcal{S}_K} \sum_{j=1}^K d_w(p_j, n_{\sigma(j)}) \quad (1.5)$$

where \mathcal{S}_K denotes the set of all permutations of K indices. Another way to compute L_w is to use the following formula (see [9]),

$$L_w = \text{Max} \sum_{j=1}^K \zeta(p_j) - \zeta(n_j), \quad (1.6)$$

where the supremum is taken over all functions $\zeta : \bar{\Omega} \rightarrow \mathbb{R}$ which are 1-Lipschitz with respect to d_w i.e., $|\zeta(x) - \zeta(y)| \leq d_w(x, y)$ for all $x, y \in \bar{\Omega}$. In Section 2.3, we give a characterization of 1-Lipschitz functions for the distance d_w . Combining this characterization with formula (1.6), we obtain the

lower bound of the energy following the approach in [9]. The upper bound is obtained using explicit test functions based on a *dipole construction*.

Section 4.1 concerns a stability property of problem (1.2). We investigate the following question. Given an arbitrary sequence $(w_n)_{n \in \mathbb{N}}$ of real measurable functions, under which condition on $(w_n)_{n \in \mathbb{N}}$, can we conclude that the sequence $\{E_{w_n}((a_i, d_i)_{i=1}^N)\}_{n \in \mathbb{N}}$ converges to $E_w((a_i, d_i)_{i=1}^N)$? From Theorem 1, we infer that the convergence of $\{E_{w_n}((a_i, d_i)_{i=1}^N)\}_{n \in \mathbb{N}}$ is strictly related to the convergence of the variational problems

$$\text{Min} \left\{ \int_0^1 \varphi_{w_n}(\gamma(t), \dot{\gamma}(t)) dt, \gamma \in \text{Lip}_{P,N}([0, 1], \overline{\Omega}) \right\}$$

where $P, N \in \Omega$ and φ_{w_n} denotes the Finsler metric derived from w_n . The same question involving the class $\text{Lip}_{P,N}([0, 1], \Omega)$ instead of the class $\text{Lip}_{P,N}([0, 1], \overline{\Omega})$ has been studied in [5] by G. Buttazzo, L. De Pascale and I. Fragalà in the Γ -convergence framework. Adapting their result to our setting, we give a necessary and sufficient condition on $(w_n)_{n \in \mathbb{N}}$ under which $\{E_{w_n}((a_i, d_i)_{i=1}^N)\}_{n \in \mathbb{N}}$ converges to $E_w((a_i, d_i)_{i=1}^N)$. In Section 4.2, we concentrate on the approximation procedure by smooth weights. If one requires that w_n is continuous and converges to w uniformly in $\overline{\Omega}$ then we get easily the convergence using formula (1.3) but such an assumption implies that w is continuous and this is quite restrictive in our setting. On the other hand if one assumes that $w_n \rightarrow w$ almost everywhere in Ω , we show that the convergence of the problems does not hold in general (c.f. Remark 4.1). However, we prove that $E_w((a_i, d_i)_{i=1}^N)$ is the limit of a sequence $\{E_{w_n}((a_i, d_i)_{i=1}^N)\}_{n \in \mathbb{N}}$ where w_n obtained from w by regularization.

In the last section, we present a partial result on a similar problem involving a matrix field $M = (m_{kl})_{k,l=1}^3$ instead of a weight:

$$E_M((a_i, d_i)_{i=1}^N) = \text{Inf}_{u \in \mathcal{E}} \int_{\Omega} \sum_{k,l=1}^3 m_{kl}(x) \frac{\partial u}{\partial x_k} \cdot \frac{\partial u}{\partial x_l} dx.$$

Throughout the paper, a sequence of smooth mollifiers means any sequence $(\rho_n)_{n \in \mathbb{N}}$ satisfying

$$\rho_n \in C^\infty(\mathbb{R}^3, \mathbb{R}), \quad \text{Supp } \rho_n \subset B_{1/n}(0), \quad \int_{\mathbb{R}^3} \rho_n = 1, \quad \rho_n \geq 0 \text{ on } \mathbb{R}^3.$$

2 Preliminary Results: Metric Properties of d_w

2.1 Metric and Geodesic Character of d_w

First of all we recall that for any metric space (M, d) , we may associate the length functional \mathbb{L}_d defined by

$$\mathbb{L}_d(\gamma) = \text{Sup} \left\{ \sum_{k=0}^{m-1} d(\gamma(t_k), \gamma(t_{k+1})), 0 = t_0 < t_1 < \dots < t_m = 1, m \in \mathbb{N} \right\}$$

where $\gamma : [0, 1] \rightarrow M$ is any continuous curve. Note that \mathbb{L}_d is lower semi-continuous on $\mathcal{C}^0([0, 1], M)$ endowed with the topology of the uniform convergence on $[0, 1]$.

Definition 2.1. A distance d is said to be *geodesic* on M if for all $x, y \in M$,

$$d(x, y) = \text{Inf } \mathbb{L}_d(\gamma)$$

where the infimum is taken over all continuous curves $\gamma : [0, 1] \rightarrow M$ such that $\gamma(0) = x$ and $\gamma(1) = y$.

Proposition 2.1. d_w defines a geodesic distance on $\bar{\Omega}$ which is equivalent to the Euclidean geodesic distance d_Ω and d_w agrees with δ_w whenever w is continuous.

Proof. Step 1. Let $x, y \in \Omega$ and let $\mathcal{F} = ([\alpha_1, \beta_1], \dots, [\alpha_n, \beta_n])$ be an element of $\mathcal{P}(x, y)$. From assumption (1.1), we get that

$$\ell_w(\mathcal{F}) \geq \sum_{k=1}^n \lim_{\varepsilon \rightarrow 0^+} \frac{\lambda}{\pi \varepsilon^2} \int_{\Xi([\alpha_k, \beta_k], \varepsilon) \cap \Omega} d\xi = \lambda \sum_{k=1}^n |\alpha_k - \beta_k| \geq \lambda d_\Omega(x, y). \quad (2.1)$$

By the definition of d_w and (1.1), for any $\mathcal{F} = ([\alpha_1, \beta_1], \dots, [\alpha_n, \beta_n])$ in $\mathcal{P}(x, y)$, we have

$$d_w(x, y) \leq \Lambda \sum_{k=1}^n \lim_{\varepsilon \rightarrow 0^+} \frac{1}{\pi \varepsilon^2} \int_{\Xi([\alpha_k, \beta_k], \varepsilon) \cap \Omega} d\xi = \Lambda \sum_{k=1}^n |\alpha_k - \beta_k|.$$

Taking the infimum over all $\mathcal{F} \in \mathcal{P}(x, y)$, we infer that

$$d_w(x, y) \leq \Lambda d_\Omega(x, y). \quad (2.2)$$

From (2.1) and (2.2), we deduce that $d_w(x, y) = 0$ if and only if $x = y$. Now let us now prove that d_w is symmetric. Let $x, y \in \Omega$ and $\delta > 0$ arbitrary small. We can find $\mathcal{F}_\delta = ([\alpha_1, \beta_2], \dots, [\alpha_n, \beta_n])$ in $\mathcal{P}(x, y)$ satisfying

$$\ell_w(\mathcal{F}_\delta) \leq d_w(x, y) + \delta.$$

Then for $\mathcal{F}'_\delta = ([\beta_n, \alpha_n], \dots, [\beta_1, \alpha_1]) \in \mathcal{P}(y, x)$, we have

$$d_w(y, x) \leq \ell_w(\mathcal{F}'_\delta) = \ell_w(\mathcal{F}_\delta) \leq d_w(x, y) + \delta.$$

Since δ is arbitrary, we obtain $d_w(y, x) \leq d_w(x, y)$ and we conclude that $d_w(y, x) = d_w(x, y)$ inverting the roles of x and y . The triangle inequality is immediate since the juxtaposition of $\mathcal{F}_1 \in \mathcal{P}(x, z)$ with $\mathcal{F}_2 \in \mathcal{P}(z, y)$ is an element of $\mathcal{P}(x, y)$. Hence d_w defines a distance on Ω verifying

$$\lambda d_\Omega(x, y) \leq d_w(x, y) \leq \Lambda d_\Omega(x, y) \quad \text{for all } x, y \in \Omega. \quad (2.3)$$

Therefore distance d_w extends uniquely to $\bar{\Omega} \times \bar{\Omega}$ into a distance function that we still denote by d_w . By continuity, d_w satisfies (2.3) on $\bar{\Omega}$.

If w is continuous, it is easy to see that for a segment $[\alpha, \beta] \subset \Omega$ we have

$$\lim_{\varepsilon \rightarrow 0^+} \frac{1}{\pi \varepsilon^2} \int_{\Xi([\alpha, \beta], \varepsilon) \cap \Omega} w(\xi) d\xi = \int_{[\alpha, \beta]} w(s) ds,$$

and we obtain for $\mathcal{F} = ([\alpha_1, \beta_1], \dots, [\alpha_n, \beta_n]) \in \mathcal{P}(x, y)$ and $x, y \in \Omega$,

$$\ell_w(\mathcal{F}) = \int_{\cup_{k=1}^n [\alpha_k, \beta_k]} w(s) ds. \quad (2.4)$$

Since w is continuous, the infimum in (1.3) can be taken over all piecewise affine curves $\gamma : [0, 1] \rightarrow \Omega$ such that $\gamma(0) = x$ and $\gamma(1) = y$ and we infer from (2.4) that $d_w(x, y) = \delta_w(x, y)$. Then $d_w \equiv \delta_w$ on $\Omega \times \Omega$ which implies that the equality holds on $\bar{\Omega} \times \bar{\Omega}$ by continuity.

Step 2. We prove the geodesic character of d_w on $\bar{\Omega}$. Since d_w is equivalent to d_Ω , $\bar{\Omega}$ endowed with d_w remains complete. By Theorem 1.8 in [16], it suffices to prove that for any $x, y \in \bar{\Omega}$ and any $\delta > 0$, we can find a point $z \in \bar{\Omega}$ verifying

$$\max(d_w(x, z), d_w(z, y)) \leq \frac{1}{2} d_w(x, y) + \delta.$$

Fix $x, y \in \bar{\Omega}$ and then $\tilde{x}, \tilde{y} \in \Omega$ such that $d_w(x, \tilde{x}) + d_w(y, \tilde{y}) \leq \delta/2$ and let $\mathcal{F} = ([\alpha_1, \beta_1], \dots, [\alpha_n, \beta_n])$ in $\mathcal{P}(x, y)$ satisfying $\ell_w(\mathcal{F}) \leq d_w(\tilde{x}, \tilde{y}) + \delta/2$. For every $1 \leq m \leq n$, we set $\mathcal{F}_m = ([\alpha_1, \beta_1], \dots, [\alpha_m, \beta_m])$. We consider $n_\star \in \mathbb{N}$ defined by

$$n_\star = \begin{cases} \text{Max} \{ m, 2 \leq m \leq n, \ell_w(\mathcal{F}_{m-1}) < \frac{1}{2} \ell_w(\mathcal{F}) \} & \text{if } \ell_w(\mathcal{F}_1) < \frac{1}{2} \ell_w(\mathcal{F}), \\ 1 & \text{otherwise,} \end{cases}$$

and $s \in (0, 1)$ defined by

$$s = \begin{cases} \frac{\ell_w(\mathcal{F}) - 2\ell_w([\alpha_1, \beta_1], \dots, [\alpha_{n_\star-1}, \beta_{n_\star-1}])}{2\ell_w([\alpha_{n_\star}, \beta_{n_\star}])} & \text{if } n_\star > 1, \\ \frac{\ell_w(\mathcal{F})}{2\ell_w([\alpha_{n_\star}, \beta_{n_\star}])} & \text{if } n_\star = 1. \end{cases}$$

Let $\varepsilon_k \rightarrow 0^+$ as $k \rightarrow +\infty$ such that

$$\ell_w([\alpha_{n_\star}, \beta_{n_\star}]) = \lim_{k \rightarrow +\infty} \frac{1}{\pi\varepsilon_k^2} \int_{\Xi([\alpha_{n_\star}, \beta_{n_\star}], \varepsilon_k) \cap \Omega} w(\xi) d\xi.$$

For each $k \in \mathbb{N}$, we choose $z_k \in [\alpha_{n_\star}, \beta_{n_\star}]$ verifying

$$\begin{aligned} \frac{1}{\pi\varepsilon_k^2} \int_{\Xi([\alpha_{n_\star}, z_k], \varepsilon_k) \cap \Omega} w(\xi) d\xi &= \frac{s}{\pi\varepsilon_k^2} \int_{\Xi([\alpha_{n_\star}, \beta_{n_\star}], \varepsilon_k) \cap \Omega} w(\xi) d\xi + \mathcal{O}(\varepsilon_k), \\ \frac{1}{\pi\varepsilon_k^2} \int_{\Xi([z_k, \beta_{n_\star}], \varepsilon_k) \cap \Omega} w(\xi) d\xi &= \frac{1-s}{2\pi\varepsilon_k^2} \int_{\Xi([\alpha_{n_\star}, \beta_{n_\star}], \varepsilon_k) \cap \Omega} w(\xi) d\xi + \mathcal{O}(\varepsilon_k). \end{aligned}$$

Extracting a subsequence if necessary, we may assume that $z_k \xrightarrow[k \rightarrow +\infty]{} z$ with $z \in [\alpha_{n_\star}, \beta_{n_\star}]$. Then we have

$$\begin{aligned} \frac{1}{\pi\varepsilon_k^2} \int_{\Xi([\alpha_{n_\star}, z], \varepsilon_k) \cap \Omega} w(\xi) d\xi &= \frac{s}{\pi\varepsilon_k^2} \int_{\Xi([\alpha_{n_\star}, \beta_{n_\star}], \varepsilon_k) \cap \Omega} w(\xi) d\xi \\ &\quad + \mathcal{O}(\varepsilon_k) + \mathcal{O}(|z - z_k|), \\ \frac{1}{\pi\varepsilon_k^2} \int_{\Xi([z, \beta_{n_\star}], \varepsilon_k) \cap \Omega} w(\xi) d\xi &= \frac{1-s}{2\pi\varepsilon_k^2} \int_{\Xi([\alpha_{n_\star}, \beta_{n_\star}], \varepsilon_k) \cap \Omega} w(\xi) d\xi \\ &\quad + \mathcal{O}(\varepsilon_k) + \mathcal{O}(|z - z_k|). \end{aligned}$$

Taking the lim inf in k , we derive

$$\ell_w([\alpha_{n_\star}, z]) \leq s\ell_w([\alpha_{n_\star}, \beta_{n_\star}]) \quad \text{and} \quad \ell_w([z, \beta_{n_\star}]) \leq (1-s)\ell_w([\alpha_{n_\star}, \beta_{n_\star}]).$$

Therefore we obtain that the elements $\mathcal{F}_{\tilde{x}} = ([\alpha_1, \beta_1], \dots, [\alpha_{n_\star}, z]) \in \mathcal{P}(\tilde{x}, z)$ and $\mathcal{F}_{\tilde{y}} = ([z, \beta_{n_\star}], \dots, [\alpha_n, \beta_n]) \in \mathcal{P}(z, \tilde{y})$ verify

$$\begin{aligned} d_w(\tilde{x}, z) &\leq \ell_w(\mathcal{F}_{\tilde{x}}) \leq \frac{1}{2} \ell_w(\mathcal{F}) \leq \frac{1}{2} d_w(\tilde{x}, \tilde{y}) + \delta/4, \\ d_w(\tilde{y}, z) &\leq \ell_w(\mathcal{F}_{\tilde{y}}) \leq \frac{1}{2} \ell_w(\mathcal{F}) \leq \frac{1}{2} d_w(\tilde{x}, \tilde{y}) + \delta/4, \end{aligned}$$

and we conclude that

$$\begin{aligned} \max(d_w(x, z), d_w(y, z)) &\leq \max(d_w(\tilde{x}, z), d_w(\tilde{y}, z)) + \frac{\delta}{2} \leq \frac{1}{2} d_w(\tilde{x}, \tilde{y}) + \frac{3\delta}{4} \\ &\leq \frac{1}{2} d_w(x, y) + \delta \end{aligned}$$

i.e. the point z meets the requirement. \blacksquare

Remark 2.1. The geodesic character of d_w implies that two arbitrary points of $(\overline{\Omega}, d_w)$ can be linked by a minimizing geodesic. We mean by a minimizing geodesic any curve $\gamma : I \rightarrow \overline{\Omega}$ such that

$$d_w(\gamma(t), \gamma(t')) = |t - t'| \quad \text{for all } t, t' \in I,$$

where I is some interval of \mathbb{R} . In particular we obtain the existence for all $x, y \in \overline{\Omega}$ of a curve $\gamma_{xy} \in \text{Lip}_{x,y}([0, 1], \overline{\Omega})$ satisfying

$$d_w(\gamma_{xy}(t), \gamma_{xy}(t')) = \mathbb{L}_{d_w}(\gamma_{xy})|t - t'| \quad \text{for all } t, t' \in [0, 1]$$

(and then $d_w(x, y) = \mathbb{L}_{d_w}(\gamma_{xy})$). Indeed, $(\overline{\Omega}, d_w)$ defines a complete and locally compact metric space and since d_w is of geodesic type, the existence of a minimizing geodesic is ensured by the Hopf-Rinow Theorem (see [16], Chapter 1). Moreover we deduce from (2.3) that any minimizing geodesic for the distance d_w is a λ^{-1} -Lipschitz curve for the Euclidean geodesic distance.

2.2 Integral Representation of the Length Functional

In this section, we show that d_w is actually induced by a Finsler metric in the sense defined below.

Definition 2.2. A Borel measurable function $\varphi : \overline{\Omega} \times \mathbb{R}^3 \rightarrow [0, +\infty)$ is said to be a *Finsler metric* if $\varphi(x, \cdot)$ is positively 1-homogeneous for every $x \in \overline{\Omega}$ and convex for almost every $x \in \overline{\Omega}$.

Proposition 2.2. *There exists a Finsler metric $\varphi_w : \overline{\Omega} \times \mathbb{R}^3 \rightarrow [0, +\infty)$ such that for every Lipschitz curve $\gamma : [0, 1] \rightarrow \overline{\Omega}$,*

$$\mathbb{L}_{d_w}(\gamma) = \int_0^1 \varphi_w(\gamma(t), \dot{\gamma}(t)) dt. \quad (2.5)$$

Moreover, for every $x, y \in \overline{\Omega}$, we have

$$d_w(x, y) = \text{Min} \left\{ \int_0^1 \varphi_w(\gamma(t), \dot{\gamma}(t)) dt, \gamma \in \text{Lip}_{x,y}([0, 1], \overline{\Omega}) \right\}. \quad (2.6)$$

Proof. Step 1. Assume that $\Omega = \mathbb{R}^3$. To distance d_w we associate the function $\varphi_w : \mathbb{R}^3 \times \mathbb{R}^3 \rightarrow [0, +\infty)$ defined by

$$\varphi_w(x, \nu) = \limsup_{t \rightarrow 0^+} \frac{d_w(x, x + t\nu)}{t}.$$

In [19], it is proved that φ_w defines a Finsler metric and the proof of (2.5) is given in [13], Theorem 2.5. Then (2.6) directly follows from Remark 2.1.

Step 2. Assume that Ω is a smooth bounded and connected open set of \mathbb{R}^3 . For $\delta > 0$, we consider $\Omega_\delta = \{x \in \mathbb{R}^3, \text{dist}(x, \Omega) < \delta\}$ where "dist" denotes the usual Euclidean distance on \mathbb{R}^3 . We choose δ sufficiently small for the projection Πx of $x \in \Omega_\delta$ on $\bar{\Omega}$ to be well defined and smooth. Setting $x_\perp = x - \Pi x$ for $x \in \Omega_\delta$, we define the function $d_{w,\delta} : \Omega_\delta \times \Omega_\delta \rightarrow [0, +\infty)$ by

$$d_{w,\delta}(x, y) = d_w(\Pi x, \Pi y) + |x_\perp - y_\perp|.$$

We easily check that $d_{w,\delta}$ defines a distance on Ω_δ . Then we consider for $x, y \in \Omega_\delta$,

$$\bar{d}_{w,\delta}(x, y) = \text{Inf } \mathbb{L}_{d_{w,\delta}}(\gamma),$$

where the infimum is taken over all $\gamma \in \mathcal{C}^0([0, 1], \Omega_\delta)$ satisfying $\gamma(0) = x$ and $\gamma(1) = y$. We also easily verify that $\bar{d}_{w,\delta}$ defines a distance on Ω_δ and it follows from Proposition 1.6 in [16] that

$$\mathbb{L}_{\bar{d}_{w,\delta}} = \mathbb{L}_{d_{w,\delta}} \quad \text{on } \mathcal{C}^0([0, 1], \Omega_\delta). \quad (2.7)$$

Therefore $\bar{d}_{w,\delta}(x, y)$ is a geodesic distance on Ω_δ . Moreover we infer from (2.3) that $\bar{d}_{w,\delta}$ is equivalent to the Euclidean geodesic distance on Ω_δ . Now we consider $\varphi_{w,\delta} : \Omega_\delta \times \mathbb{R}^3 \rightarrow [0, +\infty)$ defined by

$$\varphi_{w,\delta}(x, \nu) = \limsup_{t \rightarrow 0^+} \frac{\bar{d}_{w,\delta}(x, x + t\nu)}{t}.$$

By the results in [19], $\varphi_{w,\delta}$ is Borel measurable, positively 1-homogeneous in ν for every $x \in \Omega_\delta$ and convex in ν for almost every $x \in \Omega_\delta$. By Theorem 2.5 in [13], we have for every Lipschitz curve $\gamma : [0, 1] \rightarrow \Omega_\delta$,

$$\mathbb{L}_{\bar{d}_{w,\delta}}(\gamma) = \int_0^1 \varphi_{w,\delta}(\gamma(t), \dot{\gamma}(t)) dt. \quad (2.8)$$

Since $d_{w,\delta} = d_w$ on $\bar{\Omega}$, we deduce that

$$\mathbb{L}_{d_{w,\delta}} = \mathbb{L}_{d_w} \quad \text{on } \mathcal{C}^0([0, 1], \bar{\Omega}). \quad (2.9)$$

If we denote by φ_w the restriction of $\varphi_{w,\delta}$ to $\bar{\Omega} \times \mathbb{R}^3$, we obtain (2.5) combining (2.7-2.9). Then (2.6) follows from Remark 2.1. \blacksquare

Remark 2.2. If we assume that w is continuous in Ω , we have

$$\varphi_w(x, \nu) = w(x)|\nu| \quad \text{for every } (x, \nu) \in \Omega \times \mathbb{R}^3.$$

Indeed, fix $(x, \nu) \in \Omega \times \mathbb{R}^3 \setminus \{0\}$, $t > 0$ such that $B(x, 2t\lambda^{-1}|\nu|) \subset \Omega$ and consider a sequence $\gamma_n \in \text{Lip}([0, 1], \overline{\Omega})$ verifying

$$\int_0^1 w(\gamma_n(s)) |\dot{\gamma}_n(s)| ds \rightarrow d_w(x, x + t\nu) \quad \text{as } n \rightarrow +\infty.$$

Since $d_w \geq \lambda d_\Omega$, we infer that $\gamma_n([0, 1]) \subset B(x, 2t\lambda^{-1}|\nu|)$ and therefore

$$\int_0^1 w(\gamma_n(s)) |\dot{\gamma}_n(s)| ds \geq w(x) \int_0^1 |\dot{\gamma}_n(s)| ds - o(t) \geq w(x)t|\nu| - o(t).$$

Letting $n \rightarrow +\infty$, we obtain

$$\frac{d_w(x, x + t\nu)}{t} \geq w(x)|\nu| - o(1).$$

But we trivially have

$$\frac{d_w(x, x + t\nu)}{t} \leq \frac{1}{t} \int_0^t w(x + s\nu)|\nu| ds = w(x)|\nu| + o(1).$$

We derive the result from these two last inequalities letting $t \rightarrow 0$.

2.3 Characterization of 1-Lipschitz Functions

Proposition 2.3. *Assume that (1.1) holds. Then for all $\zeta : \overline{\Omega} \rightarrow \mathbb{R}$, the following properties are equivalent:*

- i) $|\zeta(x) - \zeta(y)| \leq d_w(x, y) \quad \text{for all } x, y \in \overline{\Omega}.$
- ii) ζ is Lipschitz continuous and $|\nabla \zeta(x)| \leq w(x)$ for a.e. $x \in \Omega$.

Proof. i) \Rightarrow ii). Let $\zeta : \overline{\Omega} \rightarrow \mathbb{R}$ satisfying i). From Proposition 2.1, we infer that ζ is Lipschitz continuous. Fix $x_0 \in \Omega$ and $R > 0$ such that $B_{3R}(x_0) \subset \Omega$. Let $(\rho_n)_{n \in \mathbb{N}}$ be a sequence of smooth mollifiers and consider, for $n > 1/R$, the smooth function $\zeta_n = \rho_n * \zeta : B_R(x_0) \rightarrow \mathbb{R}$. We write

$$\zeta_n(x) = \int_{B_{1/n}} \rho_n(-z) \zeta(x+z) dz$$

and therefore for all $x, y \in B_R(x_0)$,

$$\begin{aligned} |\zeta_n(x) - \zeta_n(y)| &\leq \int_{B_{1/n}} \rho_n(-z) |\zeta(x+z) - \zeta(y+z)| dz \\ &\leq \int_{B_{1/n}} \rho_n(-z) d_w(x+z, y+z) dz \\ &\leq \int_{B_{1/n}} \rho_n(-z) \ell_w([x+z, y+z]) dz. \end{aligned}$$

Taking an arbitrary sequence of positive numbers $\varepsilon_k \rightarrow 0$ as $k \rightarrow +\infty$ and using Fatou's lemma, we get that

$$\begin{aligned} |\zeta_n(x) - \zeta_n(y)| &\leq \int_{B_{1/n}} \rho_n(-z) \left(\liminf_{k \rightarrow +\infty} \frac{1}{\pi \varepsilon_k^2} \int_{\Xi([x+z, y+z], \varepsilon_k) \cap \Omega} w(\xi) d\xi \right) dz \\ &\leq \liminf_{k \rightarrow +\infty} \frac{1}{\pi \varepsilon_k^2} \int_{B_{1/n}} \int_{\Xi([x+z, y+z], \varepsilon_k) \cap \Omega} \rho_n(-z) w(\xi) d\xi dz. \end{aligned}$$

For $k \in \mathbb{N}$ sufficiently large, we have $\Xi([x+z, y+z], \varepsilon_k) \subset B_{3R}(x_0)$ and accordingly

$$\begin{aligned} \int_{B_{1/n}} \int_{\Xi([x+z, y+z], \varepsilon_k)} \rho_n(-z) w(\xi) d\xi dz &= \int_{\Xi([x, y], \varepsilon_k)} \int_{B_{1/n}} \rho_n(-z) w(\xi+z) dz d\xi \\ &= \int_{\Xi([x, y], \varepsilon_k)} \rho_n * w(\xi) d\xi. \end{aligned}$$

Since $\rho_n * w$ is smooth, we obtain as in the proof of Proposition 2.1,

$$\frac{1}{\pi \varepsilon_k^2} \int_{\Xi([x, y], \varepsilon_k)} \rho_n * w(\xi) d\xi \rightarrow \int_{[x, y]} \rho_n * w(s) ds \quad \text{as } k \rightarrow +\infty.$$

Thus for each $x, y \in B_R(x_0)$ we have

$$|\zeta_n(x) - \zeta_n(y)| \leq \int_{[x, y]} \rho_n * w(s) ds.$$

Then for $x \in B_R(x_0)$, $h \in S^2$ fixed and $\delta > 0$ small, we derive

$$\frac{|\zeta_n(x + \delta h) - \zeta_n(x)|}{\delta} \leq \frac{1}{\delta} \int_{[x, x + \delta h]} \rho_n * w(s) ds \xrightarrow{\delta \rightarrow 0^+} \rho_n * w(x)$$

and we conclude, letting $\delta \rightarrow 0$, that $|\nabla \zeta_n(x) \cdot h| \leq \rho_n * w(x)$ for each $x \in B_R(x_0)$ and $h \in S^2$ which implies that $|\nabla \zeta_n| \leq \rho_n * w$ on $B_R(x_0)$. Since

$\nabla\zeta_n \rightarrow \nabla\zeta$ and $\rho_n * w \rightarrow w$ a.e. on $B_R(x_0)$ as $n \rightarrow +\infty$, we deduce that $|\nabla\zeta| \leq w$ a.e. on $B_R(x_0)$. Since x_0 is arbitrary in Ω , we get the result.

ii) \Rightarrow i) The reverse implication follows from the lemma below.

Lemma 2.1. *Let $\zeta : \overline{\Omega} \rightarrow \mathbb{R}$ be a Lipschitz continuous function. For all $a, b \in \Omega$ with $[a, b] \subset \Omega$ and all $\varepsilon > 0$ sufficiently small, we have*

$$|\zeta(a) - \zeta(b)| \leq \frac{1}{\pi\varepsilon^2} \int_{\Xi([a,b],\varepsilon) \cap \Omega} |\nabla\zeta(z)| dz + 2\varepsilon \|\nabla\zeta\|_\infty.$$

Indeed, let ζ be a Lipschitz continuous function satisfying *ii*). We deduce from Lemma 2.1 and (1.1) that for all $\mathcal{F} = ([\alpha_1, \beta_1], \dots, [\alpha_n, \beta_n]) \in \mathcal{P}(x, y)$ and all parameters $\varepsilon_1, \dots, \varepsilon_n > 0$ sufficiently small, we have

$$|\zeta(x) - \zeta(y)| \leq \sum_{k=1}^n |\zeta(\beta_k) - \zeta(\alpha_k)| \leq \sum_{k=1}^n \left(\frac{1}{\pi\varepsilon_k^2} \int_{\Xi([\alpha_k, \beta_k], \varepsilon_k) \cap \Omega} w(z) dz + 2\Lambda\varepsilon_k \right).$$

Taking successively the \liminf in $\varepsilon_k \rightarrow 0^+$ for each parameter ε_k , we get that $|\zeta(x) - \zeta(y)| \leq \ell_w(\mathcal{F})$. We obtain the result for $x, y \in \Omega$ taking the infimum over all $\mathcal{F} \in \mathcal{P}(x, y)$. We conclude that *i*) holds in all $\overline{\Omega}$ by continuity. \blacksquare

Proof of Lemma 2.1. First note that we just have to prove the inequality for smooth functions ζ , the general case follows by a density argument. Let ζ be a smooth real valued function. Without loss of generality, we may assume that $a = (0, 0, 0)$ and $b = (0, 0, R)$. Then for all $\varepsilon > 0$ such that the 3D-cylinder $B_\varepsilon^{(2)}(0) \times [0, R]$ is included in Ω , and all $(x_1, x_2) \in B_\varepsilon^{(2)}(0)$, we have

$$\begin{aligned} |\zeta(b) - \zeta(a)| &\leq |\zeta(0, 0, R) - \zeta(x_1, x_2, R)| + |\zeta(x_1, x_2, R) - \zeta(x_1, x_2, 0)| \\ &\quad + |\zeta(x_1, x_2, 0) - \zeta(0, 0, 0)| \\ &\leq \int_0^R |\nabla\zeta(x_1, x_2, x_3)| dx_3 + 2\varepsilon \|\nabla\zeta\|_\infty. \end{aligned}$$

Integrating the last inequality in $(x_1, x_2) \in B_\varepsilon^{(2)}(0)$ yields

$$\pi\varepsilon^2 |\zeta(b) - \zeta(a)| \leq \int_{B_\varepsilon^{(2)}(0) \times [0, R]} |\nabla\zeta(x_1, x_2, x_3)| dx_1 dx_2 dx_3 + 2\pi\varepsilon^3 \|\nabla\zeta\|_\infty.$$

Dividing by $\pi\varepsilon^2$, we get the result since $B_\varepsilon^{(2)}(0) \times [0, R] \subset \Xi([a, b], \varepsilon) \cap \Omega$. \blacksquare

Remark 2.3. In [11], F. Camilli and A. Siconolfi study the Hamilton-Jacobi equation

$$H(x, \nabla u) = 0 \quad \text{a.e. in } \Omega$$

where the Hamiltonian $H(x, \nu)$ is measurable in x , continuous and quasi-convex in ν . They construct the *optical length function* $L^\Omega : \bar{\Omega} \times \bar{\Omega}$ giving a class of “fundamental solutions”. They show that for every $y_0 \in \bar{\Omega}$, $L^\Omega(y_0, \cdot)$ is the maximal element of the set

$$\mathcal{C}(y_0) = \{v \in W^{1,\infty}(\Omega, \mathbb{R}), H(x, \nabla v) \leq 0 \text{ a.e in } \Omega, v(y_0) = 0\}.$$

In the case $H(x, \nu) = |\nu| - w(x)$, Proposition 2.3 shows that d_w and the optical length function L^Ω coincide i.e., $d_w(x, y) = L^\Omega(x, y)$ for all $x, y \in \bar{\Omega}$.

3 Energy Estimates - Proof of Theorem 1

Theorem 1.1 follows from the combination of Lemma 3.1 and Lemma 3.4 below. In Section 3.2, we give an explicit *dipole construction*.

3.1 Lower Bound for the Energy

Lemma 3.1. *For all $u \in \mathcal{E}$, we have*

$$\int_{\Omega} |\nabla u|^2 w(x) dx \geq 8\pi L_w.$$

Proof. The proof is essentially the same as in [9] once we have the results of Section 2. We introduce for each $u \in \mathcal{E}$ the vector field D defined by

$$D = \left(u \cdot \frac{\partial u}{\partial x_2} \wedge \frac{\partial u}{\partial x_3}, u \cdot \frac{\partial u}{\partial x_3} \wedge \frac{\partial u}{\partial x_1}, u \cdot \frac{\partial u}{\partial x_1} \wedge \frac{\partial u}{\partial x_2} \right). \quad (3.1)$$

As in [9], we have $2|D| \leq |\nabla u|^2$ and $D \in L^1(\Omega)$ defines a distribution which satisfies

$$\operatorname{div} D = 4\pi \sum_{i=1}^N d_i \delta_{a_i} \quad \text{in } \mathcal{D}'(\Omega). \quad (3.2)$$

Relabelling the points (a_i) as positive and negative points taking into account their multiplicity $|d_i|$, we get a list (p_j) of positive points and a list (n_j) of negative points. Since $\sum d_i = 0$, we have as many positive points as negative points. Then we write (3.2) as

$$\operatorname{div} D = 4\pi \sum_{j=1}^K \delta_{p_j} - \delta_{n_j}. \quad (3.3)$$

From Proposition 2.3 and the properties of D , we deduce that for all functions $\zeta : \overline{\Omega} \rightarrow \mathbb{R}$ which is 1-Lipschitz with respect to d_w ,

$$\int_{\Omega} |\nabla u|^2 w(x) dx \geq 2 \int_{\Omega} |D| w(x) dx \geq -2 \int_{\Omega} D \cdot \nabla \zeta. \quad (3.4)$$

Using (3.3), we get that

$$\int_{\Omega} |\nabla u|^2 w(x) dx \geq 8\pi \left(\sum_{j=1}^K \zeta(p_j) - \zeta(n_j) \right) - 8\pi \int_{\partial\Omega} (D \cdot \eta) \zeta d\sigma$$

without the boundary term if $\Omega = \mathbb{R}^3$. On $\partial\Omega$, we have $D \cdot \eta = \text{Jac}_2(u|_{\partial\Omega})$ where η denotes the outward normal and $\text{Jac}_2(u|_{\partial\Omega})$ denotes the 2×2 Jacobian determinant of u restricted to $\partial\Omega$. Since each $u \in \mathcal{E}$ is constant on $\partial\Omega$, we have $D \cdot \eta \equiv 0$ on $\partial\Omega$ and therefore we derive

$$\int_{\Omega} |\nabla u|^2 w(x) dx \geq 8\pi \text{Max} \sum_{j=1}^K \zeta(p_j) - \zeta(n_j)$$

where the maximum is taken over all functions ζ which 1-Lipschitz with respect to d_w . By (1.6) we conclude that

$$\int_{\Omega} |\nabla u|^2 w(x) dx \geq 8\pi L_w$$

for all maps $u \in \mathcal{E}$ which completes the proof of the lower bound. \blacksquare

3.2 The Dipole Construction

Lemma 3.2. *Let P, N be two distinct points in Ω . For all $\delta > 0$, there exists $u_{\delta} \in \mathcal{C}_{\text{loc}}^1(\overline{\Omega} \setminus \{P, N\}, S^2)$ such that $\deg(u_{\delta}, P) = +1$, $\deg(u_{\delta}, N) = -1$ and*

$$\int_{\Omega} |\nabla u_{\delta}|^2 w(x) dx \leq 8\pi d_w(P, N) + \delta.$$

Moreover u_{δ} is constant outside a small neighborhood of a polygonal curve running between P and N .

Proof. For $\varepsilon > 0$, we consider the map $\omega_{\varepsilon} : \mathbb{R}^2 \rightarrow S^2$ defined by

$$\omega_{\varepsilon}(x, y) = \begin{cases} \frac{2\varepsilon^2}{\varepsilon^4 + r^2} (x, -y, -\varepsilon^2) + (0, 0, 1) & \text{if } r \leq \varepsilon \\ (A(r) \cos \theta, -A(r) \sin \theta, C(r)) & \text{if } \varepsilon \leq r \leq 2\varepsilon \\ (0, 0, 1) & \text{if } 2\varepsilon \leq r \end{cases} \quad (3.5)$$

where $(x, y) = (r \cos \theta, r \sin \theta)$ and

$$A(r) = \frac{-2\varepsilon^2}{\varepsilon^4 + \varepsilon^2} r + \frac{4\varepsilon^3}{\varepsilon^4 + \varepsilon^2}, \quad C(r) = \sqrt{1 - (A(r))^2}.$$

According to the results in [8], ω_ε is Lipschitz continuous and $\deg \omega_\varepsilon = +1$ when one identifies $\mathbb{R}^2 \cup \{\infty\}$ with S^2 . As in [9], the map ω_ε will be the main ingredient in our construction. First we define the following objects. For two distinct points $\alpha, \beta \in \Omega$ with $[\alpha, \beta] \subset \Omega$, we denote by $p_{\alpha, \beta}(x)$ the projection of $x \in \mathbb{R}^3$ on the straight line passing by α and β and

$$r_{\alpha, \beta}(x) = \text{dist}(x, [\alpha, \beta]), \quad h_{\alpha, \beta}(x) = \text{dist}(p_{\alpha, \beta}(x), \{\alpha, \beta\}),$$

where “dist” denotes the Euclidean distance in \mathbb{R}^3 . For some small $\sigma > 0$, we consider the following sets:

$$\begin{aligned} C_\varepsilon^\sigma(\alpha, \beta) &= \{x \in \mathbb{R}^3, p_{\alpha, \beta}(x) \in]\alpha, \beta[, \sigma r_{\alpha, \beta}(x) \leq h_{\alpha, \beta}(x), 0 \leq h_{\alpha, \beta}(x) \leq \sigma\varepsilon\} \\ T_\varepsilon^\sigma(\alpha, \beta) &= \{x \in \mathbb{R}^3, p_{\alpha, \beta}(x) \in [\alpha, \beta], r_{\alpha, \beta}(x) \leq \varepsilon, h_{\alpha, \beta}(x) \geq \sigma\varepsilon\} \\ V_\varepsilon(\alpha, \beta) &= \{x \in \mathbb{R}^3, p_{\alpha, \beta}(x) \in [\alpha, \beta], r_{\alpha, \beta}(x) \leq \varepsilon\}. \end{aligned}$$

We choose ε small enough such that $C_{2\varepsilon}^\sigma(\alpha, \beta) \cup T_{2\varepsilon}^\sigma(\alpha, \beta) \cup V_{2\varepsilon}(\alpha, \beta) \subset \Omega$. We fix $\delta > 0$ and we consider $\mathcal{F} = ([\alpha_1, \beta_1], \dots, [\alpha_n, \beta_n]) \in \mathcal{P}(P, N)$ such that the curve $\gamma = \cup_k [\alpha_k, \beta_k]$ has no self-intersection points. Then for each $k \in \{1, \dots, n\}$, we fix two unit vectors i_k and j_k in the orthogonal plane to $\beta_k - \alpha_k$ such that $(i_k, j_k, \frac{\beta_k - \alpha_k}{|\beta_k - \alpha_k|})$ defines a direct orthonormal basis of \mathbb{R}^3 and we consider $u_\varepsilon^{(k)} : \Omega \rightarrow S^2$ defined by

$$u_\varepsilon^{(k)}(x) = \begin{cases} \omega_\varepsilon(X_k(x), Y_k(x)) & \text{if } x \in C_{2\varepsilon}^\sigma(\alpha_k, \beta_k), \\ \omega_\varepsilon((x - p_{\alpha_k, \beta_k}(x)) \cdot i_k, (x - p_{\alpha_k, \beta_k}(x)) \cdot j_k) & \text{if } x \in T_{2\varepsilon}^\sigma(\alpha_k, \beta_k), \\ (0, 0, 1) & \text{otherwise} \end{cases}$$

with

$$X_k(x) = \frac{2\sigma\varepsilon}{h_{\alpha_k, \beta_k}(x)}(x - p_{\alpha_k, \beta_k}(x)) \cdot i_k, \quad Y_k(x) = \frac{2\sigma\varepsilon}{h_{\alpha_k, \beta_k}(x)}(x - p_{\alpha_k, \beta_k}(x)) \cdot j_k.$$

We easily check that $u_\varepsilon^{(k)} \in W_{\text{loc}}^{1, \infty}(\bar{\Omega} \setminus \{\alpha_k, \beta_k\}, S^2)$, $\deg(u_\varepsilon^{(k)}, \alpha_k) = +1$, $\deg(u_\varepsilon^{(k)}, \beta_k) = -1$. Using coordinates in the basis $(i_k, j_k, \frac{\beta_k - \alpha_k}{|\beta_k - \alpha_k|})$, some classical computations (see [6]) lead to

$$|\nabla u_\varepsilon^{(k)}(x)|^2 \leq (1 + C\varepsilon^2) \frac{4\sigma^2\varepsilon^2}{h_{\alpha_k, \beta_k}^2(x)} |\nabla \omega_\varepsilon(X_k(x), Y_k(x))|^2 \text{ in } C_{2\varepsilon}^\sigma(\alpha_k, \beta_k). \quad (3.6)$$

By the results in [8], we have

$$\int_{B_{2\varepsilon}(0) \setminus B_\varepsilon(0)} |\nabla \omega_\varepsilon|^2 = \mathcal{O}(\varepsilon), \quad \int_{B_\varepsilon(0)} |\nabla \omega_\varepsilon|^2 = 8\pi + \mathcal{O}(\varepsilon) \quad (3.7)$$

and therefore

$$\int_{(T_{2\varepsilon}^\sigma \setminus T_\varepsilon^\sigma)(\alpha_k, \beta_k)} |\nabla \omega_\varepsilon((x - p_{\alpha_k, \beta_k}(x)) \cdot i_k, (x - p_{\alpha_k, \beta_k}(x)) \cdot j_k)|^2 dx = \mathcal{O}(\varepsilon), \quad (3.8)$$

$$\int_{C_{2\varepsilon}^\sigma(\alpha_k, \beta_k)} \frac{4\sigma^2 \varepsilon^2}{h_{\alpha_k, \beta_k}^2(x)} |\nabla \omega_\varepsilon(X_k(x), Y_k(x))|^2 dx = \mathcal{O}(\varepsilon). \quad (3.9)$$

We infer from (3.6-3.9) that

$$\begin{aligned} & \int_{\Omega} |\nabla u_\varepsilon^{(k)}|^2 w(x) dx \leq \\ & \leq \int_{T_\varepsilon^\sigma(\alpha_k, \beta_k)} |\nabla \omega_\varepsilon((x - p_{\alpha_k, \beta_k}(x)) \cdot i_k, (x - p_{\alpha_k, \beta_k}(x)) \cdot j_k)|^2 w(x) dx + \mathcal{O}(\varepsilon). \end{aligned}$$

Since we have

$$|\nabla \omega_\varepsilon(x, y)|^2 = \frac{8\varepsilon^4}{(\varepsilon^4 + x^2 + y^2)^2} \quad \text{for } (x, y) \in B_\varepsilon(0),$$

we conclude that

$$\int_{\Omega} |\nabla u_\varepsilon^{(k)}|^2 w(x) dx \leq 8 \int_{V_\varepsilon(\alpha_k, \beta_k)} \frac{\varepsilon^4 w(x)}{(\varepsilon^4 + r_{\alpha_k, \beta_k}^2(x))^2} dx + \mathcal{O}(\varepsilon). \quad (3.10)$$

Then we set

$$\tilde{\ell}_w(\mathcal{F}) = \sum_{k=1}^n \liminf_{\varepsilon \rightarrow 0^+} \frac{1}{\pi} \int_{V_\varepsilon(\alpha_k, \beta_k)} \frac{\varepsilon^4 w(x)}{(\varepsilon^4 + r_{\alpha_k, \beta_k}^2(x))^2} dx. \quad (3.11)$$

By (3.10) and (3.11), we can choose $\varepsilon_1, \dots, \varepsilon_n > 0$ arbitrarily small to have

$$\sum_{k=1}^n \int_{\Omega} |\nabla u_{\varepsilon_k}^{(k)}|^2 w(x) dx \leq 8\pi \tilde{\ell}_w(\mathcal{F}) + \frac{\delta}{4}. \quad (3.12)$$

We choose σ and then each ε_k for $\{C_{2\varepsilon_k}^\sigma(\alpha_k, \beta_k) \cup T_{2\varepsilon_k}^\sigma(\alpha_k, \beta_k)\}_{k=1}^n$ to define a family of disjoint sets (which is possible since the curve γ has no self

intersection points) and such that (3.12) holds. Then we consider the map $\tilde{u}_\delta : \Omega \rightarrow S^2$ defined by

$$\tilde{u}_\delta(x) = \begin{cases} u_{\varepsilon_k}^{(k)} & \text{if } x \in C_{2\varepsilon_k}^\sigma(\alpha_k, \beta_k) \cup T_{2\varepsilon_k}^\sigma(\alpha_k, \beta_k), \\ (0, 0, 1) & \text{if } x \notin \cup_k C_{2\varepsilon_k}^\sigma(\alpha_k, \beta_k) \cup T_{2\varepsilon_k}^\sigma(\alpha_k, \beta_k). \end{cases}$$

By construction, $\tilde{u}_\delta \in W_{\text{loc}}^{1,\infty}(\overline{\Omega} \setminus \{P, \alpha_2, \dots, \alpha_n, N\}, S^2)$, $\deg(\tilde{u}_\delta, P) = 1$, $\deg(\tilde{u}_\delta, N) = -1$ and $\deg(\tilde{u}_\delta, \alpha_k) = 0$ for $k = 2, \dots, n$. From (3.12), we derive that

$$\int_{\Omega} |\nabla \tilde{u}_\delta|^2 w(x) dx \leq 8\pi \tilde{\ell}_w(\mathcal{F}) + \frac{\delta}{4}.$$

Since $\deg(\tilde{u}_\delta, \alpha_k) = 0$ for $k = 2, \dots, n$, we can smoothen \tilde{u}_δ around γ , using the result in [2], in order to obtain a new map $u_\delta \in \mathcal{C}_{\text{loc}}^1(\overline{\Omega} \setminus \{P, N\}, S^2)$ verifying $\deg(u_\delta, P) = 1$, $\deg(u_\delta, N) = -1$ and

$$\int_{\Omega} |\nabla u_\delta|^2 w(x) dx \leq 8\pi \tilde{\ell}_w(\mathcal{F}) + \frac{\delta}{2}. \quad (3.13)$$

Now we recall that the collection $\mathcal{F} = ([\alpha_1, \beta_1], \dots, [\alpha_n, \beta_n]) \in \mathcal{P}(P, N)$ such that the curve $\gamma = \cup_k [\alpha_k, \beta_k]$ has no self-intersection points, can be chosen for the construction of u_δ . From Lemma 3.3 below, we can find \mathcal{F} such that

$$\tilde{\ell}_w(\mathcal{F}) \leq d_w(P, N) + \frac{\delta}{16\pi}$$

and according to (3.13), the map u_δ satisfies the required properties. \blacksquare

Lemma 3.3. *For any $x, y \in \Omega$, let $\mathcal{P}'(x, y)$ be the class of all elements $\mathcal{F} = ([\alpha_1, \beta_1], \dots, [\alpha_n, \beta_n])$ in $\mathcal{P}(x, y)$ such that the curve $\gamma = \cup_k [\alpha_k, \beta_k]$ has no self intersection points. Then*

$$\tilde{d}_w(x, y) = \inf_{\mathcal{F} \in \mathcal{P}'(x, y)} \tilde{\ell}_w(\mathcal{F}) \leq d_w(x, y),$$

where $\tilde{\ell}_w(\mathcal{F})$ is defined in (3.11).

Proof. Step 1. First we prove that \tilde{d}_w defines a distance. As for distance d_w , we infer that $\tilde{d}_w(x, y) = 0$ if and only if $x = y$ and \tilde{d}_w is symmetric. Then we just have to check the triangle inequality. We remark that the juxtaposition of $\mathcal{F}_1 \in \mathcal{P}'(x, z)$ with $\mathcal{F}_2 \in \mathcal{P}'(z, y)$ is not an element of $\mathcal{P}'(x, y)$ in general and we can't proceed as for d_w . Let x, y, z be three distinct points in Ω . We consider two arbitrary elements $\mathcal{F}_1 = ([\alpha_1^1, \beta_1^1], \dots, [\alpha_{n_1}^1, \beta_{n_1}^1]) \in \mathcal{P}'(x, z)$,

$\mathcal{F}_2 = ([\alpha_1^2, \beta_1^2], \dots, [\alpha_{n_2}^2, \beta_{n_2}^2]) \in \mathcal{P}'(z, y)$, and the curves $\gamma_1 = \cup_k [\alpha_k^1, \beta_k^1]$ and $\gamma_2 = \cup_k [\alpha_k^2, \beta_k^2]$. We have to prove that we can construct $\mathcal{F}_3 \in \mathcal{P}'(x, y)$ such that $\tilde{\ell}_w(\mathcal{F}_3) \leq \tilde{\ell}_w(\mathcal{F}_1) + \tilde{\ell}_w(\mathcal{F}_2)$.

First Case: If the curve $\gamma_1 \cup \gamma_2$ has no self intersection points then we take $\mathcal{F}_3 = ([\alpha_1^1, \beta_1^1], \dots, [\alpha_{n_1}^1, \beta_{n_1}^1], [\alpha_1^2, \beta_1^2], \dots, [\alpha_{n_2}^2, \beta_{n_2}^2]) \in \mathcal{P}'(x, y)$ and we have

$$\tilde{\ell}_w(\mathcal{F}_3) = \tilde{\ell}_w(\mathcal{F}_1) + \tilde{\ell}_w(\mathcal{F}_2).$$

Second Case: If $\gamma_1 \cup \gamma_2$ has self intersection points then we rewrite the curves γ_1 and γ_2 as $\gamma_1 = \cup_{k=1}^{\tilde{n}_1} [\tilde{\alpha}_k^1, \tilde{\beta}_k^1]$ and $\gamma_2 = \cup_{k=1}^{\tilde{n}_2} [\tilde{\alpha}_k^2, \tilde{\beta}_k^2]$ such that

- a) $(\alpha_k^i)_{k=1}^{n_i} \subset (\tilde{\alpha}_k^i)_{k=1}^{\tilde{n}_i}$ for $i = 1, 2$,
- b) if S is a connected component of $\gamma_1 \cap \gamma_2$ then one of the following cases holds:
 - b1) $S \subset \left(\cup_{k=1}^{\tilde{n}_1} \{\tilde{\alpha}_k^1, \tilde{\beta}_k^1\} \right) \cap \left(\cup_{k=1}^{\tilde{n}_2} \{\tilde{\alpha}_k^2, \tilde{\beta}_k^2\} \right)$,
 - b2) $S \in \left\{ [\tilde{\alpha}_1^1, \tilde{\beta}_1^1], \dots, [\tilde{\alpha}_{\tilde{n}_1}^1, \tilde{\beta}_{\tilde{n}_1}^1] \right\} \cap \left\{ [\tilde{\alpha}_1^2, \tilde{\beta}_1^2], \dots, [\tilde{\alpha}_{\tilde{n}_2}^2, \tilde{\beta}_{\tilde{n}_2}^2] \right\}$,
- c) $\tilde{\mathcal{F}}_1 = ([\tilde{\alpha}_1^1, \tilde{\beta}_1^1], \dots, [\tilde{\alpha}_{\tilde{n}_1}^1, \tilde{\beta}_{\tilde{n}_1}^1]) \in \mathcal{P}'(x, z)$,
- d) $\tilde{\mathcal{F}}_2 = ([\tilde{\alpha}_1^2, \tilde{\beta}_1^2], \dots, [\tilde{\alpha}_{\tilde{n}_2}^2, \tilde{\beta}_{\tilde{n}_2}^2]) \in \mathcal{P}'(z, y)$.

By construction, we can write $[\alpha_k^i, \beta_k^i] = \cup_{l=1}^{m_k^i} [\tilde{\alpha}_l^i, \tilde{\beta}_l^i]$ for some $m_k^i \in \mathbb{N}$ and for any $k = 1, \dots, n_i$ and $i = 1, 2$. Since we have

$$V_\varepsilon(\alpha_k^i, \beta_k^i) = \cup_{l=1}^{m_k^i} V_\varepsilon(\tilde{\alpha}_l^i, \tilde{\beta}_l^i),$$

we get that

$$\begin{aligned} \liminf_{\varepsilon \rightarrow 0^+} \frac{1}{\pi} \int_{V_\varepsilon(\alpha_k^i, \beta_k^i)} \frac{\varepsilon^4 w(x)}{\left(\varepsilon^4 + r_{\alpha_k^i, \beta_k^i}^2(x) \right)^2} dx &\geq \\ &\geq \sum_{l=1}^{m_k^i} \liminf_{\varepsilon \rightarrow 0^+} \frac{1}{\pi} \int_{V_\varepsilon(\tilde{\alpha}_l^i, \tilde{\beta}_l^i)} \frac{\varepsilon^4 w(x)}{\left(\varepsilon^4 + r_{\tilde{\alpha}_l^i, \tilde{\beta}_l^i}^2(x) \right)^2} dx \end{aligned}$$

and we conclude that $\tilde{\ell}_w(\tilde{\mathcal{F}}_i) \leq \tilde{\ell}_w(\mathcal{F}_i)$ for $i = 1, 2$. In the collection $([\tilde{\alpha}_1^1, \tilde{\beta}_1^1], \dots, [\tilde{\alpha}_{\tilde{n}_1}^1, \tilde{\beta}_{\tilde{n}_1}^1], [\tilde{\alpha}_1^2, \tilde{\beta}_1^2], \dots, [\tilde{\alpha}_{\tilde{n}_2}^2, \tilde{\beta}_{\tilde{n}_2}^2])$, we just have to delete some segments in order to obtain a new element $\mathcal{F}_3 \in \mathcal{P}'(x, y)$ which then satisfies

$$\tilde{\ell}_w(\mathcal{F}_3) \leq \tilde{\ell}_w(\tilde{\mathcal{F}}_1) + \tilde{\ell}_w(\tilde{\mathcal{F}}_2) \leq \tilde{\ell}_w(\mathcal{F}_1) + \tilde{\ell}_w(\mathcal{F}_2).$$

From these constructions, we conclude that $\tilde{d}_w(x, y) \leq \tilde{\ell}_w(\mathcal{F}_1) + \tilde{\ell}_w(\mathcal{F}_2)$. Taking the infimum over all $\mathcal{F}_1 \in \mathcal{P}'(x, z)$ and all $\mathcal{F}_2 \in \mathcal{P}'(z, y)$, we derive the triangle inequality.

Step 2. We fix two arbitrary points x_0 and y_0 in Ω and we consider $\zeta : \Omega \rightarrow \mathbb{R}$ defined by

$$\zeta(x) = \tilde{d}_w(x, y_0).$$

From the triangle inequality, we get that ζ is 1-Lipschitz with respect to the distance \tilde{d}_w . Let $z_0 \in \Omega$ and $R > 0$ such that $B_{3R}(z_0) \subset \Omega$ and let $(\rho_n)_{n \in \mathbb{N}}$ be a sequence of smooth mollifiers. For $n > 1/R$, we consider $\zeta_n = \rho_n * \zeta : B_R(z_0) \rightarrow \mathbb{R}$. We have for all $x, y \in B_R(z_0)$,

$$\begin{aligned} |\zeta_n(x) - \zeta_n(y)| &\leq \int_{B_{1/n}} \rho_n(-z) |\zeta(x+z) - \zeta(y+z)| dz \\ &\leq \int_{B_{1/n}} \rho_n(-z) \tilde{d}_w(x+z, y+z) dz \\ &\leq \int_{B_{1/n}} \rho_n(-z) \tilde{\ell}_w([x+z, y+z]) dz. \end{aligned}$$

We remark that $V_\varepsilon(x+z, y+z) = z + V_\varepsilon(x, y)$ and that for all $\xi \in V_\varepsilon(x, y)$, we have $r_{x,y}(\xi) = r_{x+z, y+z}(\xi+z)$. Then we obtain for all $z \in B_{1/n}(0)$,

$$\tilde{\ell}_w([x+z, y+z]) = \liminf_{\varepsilon \rightarrow 0^+} \frac{1}{\pi} \int_{V_\varepsilon(x,y)} \frac{\varepsilon^4 w(\xi+z)}{(\varepsilon^4 + r_{x,y}^2(\xi))^2} d\xi.$$

Taking an arbitrary sequence $\varepsilon_k \rightarrow 0^+$ and using Fatou's lemma, we get that

$$\begin{aligned} |\zeta_n(x) - \zeta_n(y)| &\leq \liminf_{k \rightarrow +\infty} \frac{1}{\pi} \int_{B_{1/n}} \int_{V_{\varepsilon_k}(x,y)} \frac{\varepsilon_k^4 \rho_n(-z) w(\xi+z)}{(\varepsilon_k^4 + r_{x,y}^2(\xi))^2} d\xi dz \\ &\leq \liminf_{k \rightarrow +\infty} \frac{1}{\pi} \int_{V_{\varepsilon_k}(x,y)} \frac{\varepsilon_k^4}{(\varepsilon_k^4 + r_{x,y}^2(\xi))^2} \rho_n * w(\xi) d\xi. \end{aligned}$$

Without loss of generality we may assume that $[x, y] = \{(0, 0)\} \times [-R, R]$. Then we have $V_\varepsilon(x, y) = \{(\xi_1, \xi_2, \xi_3) \in \mathbb{R}^3, |\xi_3| \leq R, \sqrt{\xi_1^2 + \xi_2^2} \leq \varepsilon\}$ and

$r_{x,y}(\xi) = \sqrt{\xi_1^2 + \xi_2^2}$ for $\xi \in V_\varepsilon(x, y)$. Therefore we can write

$$\begin{aligned} \int_{V_{\varepsilon_k}(x,y)} \frac{\varepsilon_k^4 \rho_n * w(\xi)}{(\varepsilon_k^4 + r_{x,y}^2(\xi))^2} d\xi &= \int_{B_{\varepsilon_k}(0) \times [-R, R]} \frac{\varepsilon_k^4 \rho_n * w(\xi)}{(\varepsilon_k^4 + \xi_1^2 + \xi_2^2)^2} d\xi \\ &= \int_{B_{\varepsilon_k}(0) \times [-R, R]} \frac{\varepsilon_k^4 (\rho_n * w(0, 0, \xi_3) + \mathcal{O}_n(\varepsilon_k))}{(\varepsilon_k^4 + \xi_1^2 + \xi_2^2)^2} d\xi, \end{aligned}$$

where $\mathcal{O}_n(\varepsilon_k)$ denotes a quantity which tends to 0 as $\varepsilon_k \rightarrow 0$ for n fixed. Since we have

$$\int_{B_{\varepsilon_k}(0)} \frac{\varepsilon_k^4}{(\varepsilon_k^4 + \xi_1^2 + \xi_2^2)^2} d\xi = \pi + \mathcal{O}(\varepsilon_k),$$

it follows that

$$|\zeta_n(x) - \zeta_n(y)| \leq \int_{-R}^R \rho_n * w(0, 0, \xi_3) d\xi_3 = \int_{[x,y]} \rho_n * w(s) ds.$$

As in the proof of Proposition 2.3, we conclude that $|\nabla\zeta| \leq w$ a.e. in $B_R(z_0)$ and since z_0 is arbitrary in Ω , we get that $|\nabla\zeta| \leq w$ a.e. in Ω . According to Proposition 2.3, it implies that for all $x, y \in \Omega$,

$$|\zeta(x) - \zeta(y)| \leq d_w(x, y)$$

which leads to $\tilde{d}_w(x_0, y_0) \leq d_w(x_0, y_0)$ taking $x = x_0$ and $y = y_0$. ■

3.3 Upper Bound for the Energy

Lemma 3.4. *For all $\delta > 0$, there exists a map $u_\delta \in \mathcal{E}$ such that*

$$\int_{\Omega} |\nabla u_\delta|^2 w(x) dx \leq 8\pi L_w + \delta.$$

Proof. We relabel the list $(a_i)_{i=1}^N$ as a list of positive points $(p_j)_{j=1}^K$ and a list of negative points $(n_j)_{j=1}^K$ and we may assume that $\sum_j d_w(p_j, n_j) = L_w$. We will construct dipoles between each pair (p_j, n_j) which do not intersect each other. We claim that we can find $\mathcal{F}_1 = ([\alpha_1^1, \beta_1^1], \dots, [\alpha_{m_1}^1, \beta_{m_1}^1]) \in \mathcal{P}'(p_1, n_1)$ such that

$$(A.1) \quad \gamma_1 = \cup_k [\alpha_k^1, \beta_k^1] \text{ does not contain any } p_j \neq p_1 \text{ and any } n_j \neq n_1,$$

$$(A.2) \quad \tilde{\ell}_w(\mathcal{F}_1) \leq d_w(p_1, n_1) + \frac{\delta}{8K\pi}.$$

Indeed if we define for $x, y \in \Omega_A = \Omega \setminus \{p_j, n_j | p_j \neq p_1, n_j \neq n_1\}$,

$$D_w^A(x, y) = \text{Inf } \tilde{\ell}_w(\mathcal{F})$$

where the infimum is taken over all $\mathcal{F} = ([\alpha_1, \beta_1], \dots, [\alpha_m, \beta_m]) \in \mathcal{P}'(x, y)$ such that $\cup_k [\alpha_k, \beta_k] \subset \Omega_A$ then we prove, using the arguments in the proof of Lemma 3.3 that $D_w^A(x, y) \leq d_w(x, y)$ for all $x, y \in \Omega_A$. Since $p_1, n_1 \in \Omega_A$, we obtain $D_w^A(p_1, n_1) \leq d_w(p_1, n_1)$ and by the definition of D_w^A , we draw the existence of $\mathcal{F}_1 \in \mathcal{P}'(p_1, n_1)$ satisfying (A.1) and (A.2).

Now we will show that we can find $\mathcal{F}_2 = ([\alpha_1^2, \beta_1^2], \dots, [\alpha_{m_2}^2, \beta_{m_2}^2])$ in $\mathcal{P}'(p_2, n_2)$ such that

(B.1) $\gamma_2 = \cup_k [\alpha_k^2, \beta_k^2]$ does not contain any $p_j \neq p_2$ and any $n_j \neq n_2$ and does not intersect $\gamma_1 \setminus \{p_1, n_1\}$,

(B.2) $\tilde{\ell}_w(\mathcal{F}_2) \leq d_w(p_2, n_2) + \frac{\delta}{8K\pi}$.

As previously we define

$$\Omega_B = \Omega \setminus (\{p_j, n_j | p_j \neq p_2, n_j \neq n_2\} \cup \gamma_1 \setminus \{p_1, n_1\})$$

and

$$D_w^B(x, y) = \text{Inf } \tilde{\ell}_w(\mathcal{F}) \quad \text{for } x, y \in \Omega_B$$

where the infimum is taken over all $\mathcal{F} = ([\alpha_1, \beta_1], \dots, [\alpha_m, \beta_m]) \in \mathcal{P}'(x, y)$ such that $\cup_k [\alpha_k, \beta_k] \subset \Omega_B$. In the same way we infer that for all $x, y \in \Omega_2$, $D_w^B(x, y) \leq d_w(x, y)$ and the existence of $\mathcal{F}_2 \in \mathcal{P}'(p_2, n_2)$ satisfying (B.1) and (B.2) follows.

Iterating this process, we finally reach the existence of K elements $\mathcal{F}_j = ([\alpha_1^j, \beta_1^j], \dots, [\alpha_{m_j}^j, \beta_{m_j}^j])$ in $\mathcal{P}'(p_j, n_j)$ such that $\tilde{\ell}_w(\mathcal{F}_j) \leq d_w(p_j, n_j) + \frac{\delta}{8K\pi}$, $\gamma_j = \cup_k [\alpha_k^j, \beta_k^j]$ and $\gamma_i = \cup_k [\alpha_k^i, \beta_k^i]$ do not intersect except maybe at their extremities for $i \neq j$. From the dipole construction in Lemma 3.2, we find K maps $u_\delta^j \in C_{\text{loc}}^1(\bar{\Omega} \setminus \{p_j, n_j\}, S^2)$ constant outside an arbitrary small open neighborhood \mathcal{N}_j of γ_j and such that $\deg(u_\delta^j, p_j) = +1$, $\deg(u_\delta^j, n_j) = -1$ and

$$\int_{\Omega} |\nabla u_\delta^j|^2 w(x) dx \leq 8\pi d_w(p_j, n_j) + \frac{\delta}{K}.$$

By construction of the \mathcal{F}_j 's, we can choose the \mathcal{N}_j sufficiently small for \mathcal{N}_j and \mathcal{N}_i to not intersect whenever $j \neq i$. Then the map

$$u_\delta(x) = \begin{cases} u_\delta^j(x) & \text{if } x \in \mathcal{N}_j, \\ (0, 0, 1) & \text{if } x \notin \cup_j \mathcal{N}_j, \end{cases}$$

is well defined and satisfies the required properties. ■

Remark 3.1. In a forthcoming paper (see [18]), we study, in the case of a smooth bounded open set $\Omega \subset \mathbb{R}^3$, the *relaxed energy* defined for $u \in H_g^1(\Omega, S^2)$ by

$$E_w(u) = \text{Inf} \left\{ \liminf_{n \rightarrow +\infty} \int_{\Omega} |\nabla u_n(x)|^2 w(x) dx \right\}$$

where the infimum is taken over all sequences $(u_n)_{n \in \mathbb{N}} \subset \mathcal{C}^1(\overline{\Omega}, S^2)$ satisfying $u_n|_{\partial\Omega} = g$, $u_n \rightarrow u$ weakly in H^1 and $g : \partial\Omega \rightarrow S^2$ is a given smooth map such that $\deg(g, \partial\Omega) = 0$. In the case $w \equiv 1$, F. Bethuel, H. Brezis and J.M. Coron have proved (see [3]) that

$$E_1(u) = \int_{\Omega} |\nabla u(x)|^2 dx + 8\pi L(u)$$

where $L(u)$ denotes the length of a minimal connection (relative to the Euclidean geodesic distance d_{Ω} in Ω) between the singularities of u . We believe that a similar result holds for any function w satisfying (1.1), computing minimal connections with d_w instead of d_{Ω} .

4 Some Stability and Approximation Results

4.1 Stability Results

The stability result below is based on Theorem 3.1 in [5]. It relies on the Γ -convergence of the length functionals (we refer to [12] for the notion of Γ -convergence). In the sequel, we denote by $\text{Lip}([0, 1], \overline{\Omega})$ the class of all Lipschitz map from $[0, 1]$ into $\overline{\Omega}$ and we endow $\text{Lip}([0, 1], \overline{\Omega})$ with the topology of the uniform convergence on $[0, 1]$.

Theorem 4.1. *Let $(w_n)_{n \in \mathbb{N}}$ be a sequence of measurable real functions such that*

$$0 < c_0 \leq w_n \leq C_0 \quad \text{a.e in } \Omega$$

for some constants c_0 and C_0 independent of $n \in \mathbb{N}$. Then the following properties are equivalent:

(i) $E_{w_n}((a_i, d_i)_{i=1}^N) \xrightarrow{n \rightarrow +\infty} E_w((a_i, d_i)_{i=1}^N)$ for any configuration $(a_i, d_i)_{i=1}^N$,

(ii) the functionals $\mathbb{L}_{d_{w_n}}$ Γ -converge to \mathbb{L}_{d_w} in $\text{Lip}([0, 1], \overline{\Omega})$.

In the proof of Theorem 4.1, we will make use of the following lemma.

Lemma 4.1. *Let $(d_n)_{n \in \mathbb{N}}$ be a sequence of geodesic distances on $\overline{\Omega}$ such that*

$$c_0 d_\Omega \leq d_n \leq C_0 d_\Omega \quad (4.1)$$

for some positive constants c_0 and C_0 independent of $n \in \mathbb{N}$. Then there exists a subsequence $(n_k)_{k \in \mathbb{N}}$ and a geodesic distance d' on $\overline{\Omega}$ such that $d_{n_k} \rightarrow d'$ as $k \rightarrow +\infty$ uniformly on every compact subset of $\overline{\Omega} \times \overline{\Omega}$.

Proof. For $(x_1, y_1), (x_2, y_2) \in \overline{\Omega} \times \overline{\Omega}$ we have

$$\begin{aligned} d_{w_n}(x_1, y_1) - d_{w_n}(x_2, y_2) &\leq d_{w_n}(x_1, x_2) + d_{w_n}(x_2, y_1) - d_{w_n}(x_2, y_2) \\ &\leq d_{w_n}(x_1, x_2) + d_{w_n}(y_1, y_2) \\ &\leq C_0 (d_\Omega(x_1, x_2) + d_\Omega(y_1, y_2)). \end{aligned}$$

Inverting the roles of (x_1, y_1) and (x_2, y_2) we infer that

$$|d_{w_n}(x_1, y_1) - d_{w_n}(x_2, y_2)| \leq C_0 (d_\Omega(x_1, x_2) + d_\Omega(y_1, y_2)).$$

Thus d_{w_n} is C_0 -Lipschitz on $\overline{\Omega} \times \overline{\Omega}$ for every $n \in \mathbb{N}$ and we conclude by Ascoli's theorem that we can find a subsequence $(n_k)_{k \in \mathbb{N}}$ and a Lipschitz function d' on $\overline{\Omega} \times \overline{\Omega}$ such that $d_{n_k} \rightarrow d'$ as $k \rightarrow +\infty$ uniformly on every compact subset of $\overline{\Omega} \times \overline{\Omega}$. We easily check that d' defines a distance on $\overline{\Omega}$ and it remains to prove that d' is geodesic. Since d' satisfies (4.1) as the pointwise limit of $(d_{n_k})_{k \in \mathbb{N}}$, $\overline{\Omega}$ endowed with d' is a complete metric space. By Theorem 1.8 in [16], it suffices to prove that for any $x, y \in \overline{\Omega}$ and $\delta > 0$ there exists $z \in \overline{\Omega}$ such that $\max(d'(x, z), d'(z, y)) \leq \frac{1}{2} d'(x, y) + \delta$. We fix $x, y \in \overline{\Omega}$ and $\delta > 0$. Since d_{n_k} is of geodesic type, we can find $z_k \in \overline{\Omega}$ such that $\max(d_{n_k}(x, z), d_{n_k}(z, y)) \leq \frac{1}{2} d_{n_k}(x, y) + \delta$. Then the sequence (z_k) is bounded and we may assume that $z_k \rightarrow z \in \overline{\Omega}$. Since $d_{n_k} \rightarrow d'$ uniformly on every compact subset of $\overline{\Omega} \times \overline{\Omega}$, we deduce that $d_{n_k}(x, z_k) \rightarrow d'(x, z)$ and $d_{n_k}(z_k, y) \rightarrow d'(z, y)$. Letting $k \rightarrow +\infty$ in the last inequality we draw that z satisfies the requirement. \blacksquare

Proof of Theorem 4.1. Step 1. We prove $(i) \Rightarrow (ii)$. From (i) we derive that $E_{w_n}(P, N) \rightarrow E_w(P, N)$ in the dipole case for any distinct points $P, N \in \Omega$. By Theorem 1.1 we conclude that $d_{w_n} \rightarrow d_w$ pointwise on Ω . As in the proof of Proposition 2.1 we have $c_0 d_\Omega \leq d_{w_n} \leq C_0 d_\Omega$ in $\overline{\Omega}$. By Lemma 4.1 and the uniqueness of the limit we get that $d_{w_n} \rightarrow d_w$ uniformly on every compact subset of $\overline{\Omega} \times \overline{\Omega}$. Using the arguments of the proof of $(i) \Rightarrow (ii)$ Theorem 3.1 in [5], we infer that $\mathbb{L}_{d_{w_n}} \xrightarrow{\Gamma} \mathbb{L}_{d_w}$ in $\text{Lip}([0, 1], \overline{\Omega})$.

Step 2. We prove $(ii) \Rightarrow (i)$. Since we have $c_0 d_\Omega \leq d_{w_n} \leq C_0 d_{w_n}$ in $\overline{\Omega}$

we draw from Lemma 4.1 that we can find a subsequence $(n_k)_{k \in \mathbb{N}}$ and a geodesic distance d' on $\overline{\Omega}$ such that $d_{w_{n_k}} \rightarrow d'$ uniformly on every compact subset of $\overline{\Omega} \times \overline{\Omega}$. As in the previous step, we obtain using the method in [5] that $\mathbb{L}_{d_{w_{n_k}}} \xrightarrow{\Gamma} \mathbb{L}_{d'}$ in $\text{Lip}([0, 1], \overline{\Omega})$. Then we conclude by assumption (ii) that $\mathbb{L}_{d'} \equiv \mathbb{L}_{d_w}$ on $\text{Lip}([0, 1], \overline{\Omega})$. Since $c_0 d_\Omega \leq d' \leq C_0 d_\Omega$ as the pointwise limit of $(d_{w_{n_k}})_{k \in \mathbb{N}}$, we can proceed as in Remark 2.1 to prove that for any $x, y \in \overline{\Omega}$ there exists a curve $\gamma \in \text{Lip}([0, 1], \overline{\Omega})$ such that $d'(x, y) = \mathbb{L}_{d'}(\gamma)$. Since the same property holds for d_w we finally get that $d' \equiv d_w$. The uniqueness of the limit implies the convergence of the full sequence. Then (i) follows by Theorem 1.1. \blacksquare

In the next proposition, we give some sufficient conditions on a sequence $(w_n)_{n \in \mathbb{N}}$ converging pointwise to w for Property (i) in Theorem 4.1 to hold.

Proposition 4.1. *Let $(w_n)_{n \in \mathbb{N}}$ be a sequence of measurable functions such that*

$$0 < c_0 \leq w_n \leq C_0 \quad \text{a.e. in } \Omega$$

for some constants c_0 and C_0 independent of $n \in \mathbb{N}$. Assume that one of the following conditions holds:

- (a) $w_n \geq w$ and $w_n \rightarrow w$ a.e. in Ω ,
- (b) $w_n \rightarrow w$ in $L^\infty(\Omega)$.

Then Property (i) in Theorem 4.1 holds.

Proof. Step 1. Assume that (a) holds. Since $w \leq w_n$ a.e. in Ω we infer that $E_w((a_i, d_i)_{i=1}^N) \leq E_{w_n}((a_i, d_i)_{i=1}^N)$ for any $n \in \mathbb{N}$ and therefore

$$E_w((a_i, d_i)_{i=1}^N) \leq \liminf_{n \rightarrow +\infty} E_{w_n}((a_i, d_i)_{i=1}^N). \quad (4.2)$$

Fix some $u \in \mathcal{E}$. Since $w_n \leq C_0$ and $w_n \rightarrow w$ a.e. on Ω , we obtain by dominated convergence that

$$\int_{\Omega} |\nabla u|^2 w_n(x) dx \xrightarrow{n \rightarrow +\infty} \int_{\Omega} |\nabla u|^2 w(x) dx.$$

Then we derive

$$\limsup_{n \rightarrow +\infty} E_{w_n}((a_i, d_i)_{i=1}^N) \leq \int_{\Omega} |\nabla u|^2 w(x) dx,$$

and since u is arbitrary we conclude

$$\limsup_{n \rightarrow +\infty} E_{w_n}((a_i, d_i)_{i=1}^N) \leq E_w((a_i, d_i)_{i=1}^N). \quad (4.3)$$

Finally the announced result follows from (4.2) and (4.3).

Step 2. Assume that (b) holds. We consider $\delta_n = \|w_n - w\|_{L^\infty(\Omega)}$ and

$$\tilde{w}_n = (1 + c_0^{-1}\delta_n)w_n.$$

By construction we have $\tilde{w}_n \geq w$ and $\tilde{w}_n \rightarrow w$ a.e. in Ω . From the previous case we deduce that

$$\lim_{n \rightarrow +\infty} E_{\tilde{w}_n}((a_i, d_i)_{i=1}^N) = E_w((a_i, d_i)_{i=1}^N),$$

which leads to the result since $E_{\tilde{w}_n}((a_i, d_i)_{i=1}^N) = (1 + c_0^{-1}\delta_n)E_{w_n}((a_i, d_i)_{i=1}^N)$ and $1 + c_0^{-1}\delta_n \rightarrow 1$. \blacksquare

Remark 4.1. The conclusion of Proposition 4.1 case (b) may fail if the sequence $\{w_n\}$ converges to w almost everywhere in Ω . Indeed, if one considers a sequence $(w_n)_{n \in \mathbb{N}}$ of smooth functions on $\Omega = B_1(0)$ satisfying

$$w_n(x) = \begin{cases} 1 & \text{if } |x_3| \geq 1/n, \\ 1/2 & \text{if } |x_3| = 0, \end{cases}$$

and $1/2 \leq w_n \leq 1$ in Ω , one can easily check that $w_n \rightarrow 1$ in $L^p(\Omega)$ for any $1 \leq p < +\infty$. Now if we choose two distinct points $P, N \in \{(x_1, x_2, 0) \in \Omega\}$, we obtain in the dipole case $E_{w_n}(P, N) = 1/2|P - N|$ for any $n \in \mathbb{N}$ and $E_1(P, N) = |P - N|$. Note that if we consider the sequence of variational problems

$$P_n = \text{Min} \left\{ \int_{\Omega} |\nabla u(x)|^2 w_n(x) dx, u \in H_g^1(\Omega, \mathbb{R}) \right\},$$

where g denotes some given function in $H^{1/2}(\partial\Omega, \mathbb{R})$, then it follows by classical results (see [12] for instance) that

$$P_n \xrightarrow{n \rightarrow +\infty} \text{Min} \left\{ \int_{\Omega} |\nabla u(x)|^2 dx, u \in H_g^1(\Omega, \mathbb{R}) \right\}.$$

4.2 Approximation Result

In this section, we give an approximation procedure by smooth weights.

Theorem 4.2. *Let $(\rho_n)_{n \in \mathbb{N}}$ be a sequence of smooth mollifiers. Extending w outside Ω by a sufficiently large positive constant and taking $w_n = \rho_n * w$, we have*

$$E_{w_n}((a_i, d_i)_{i=1}^N) \rightarrow E_w((a_i, d_i)_{i=1}^N) \quad \text{as } n \rightarrow +\infty.$$

Proof. Step 1. Assume that $\Omega = \mathbb{R}^3$. Let $(\rho_n)_{n \in \mathbb{N}}$ be a sequence of smooth mollifiers. Fix any function ζ which is 1-Lipschitz with respect to d_w . Using the arguments in the proof of Proposition 2.3, we obtain that the function $\zeta_n = \rho_n * \zeta$ satisfies $|\nabla \zeta_n| \leq \rho_n * w$ on \mathbb{R}^3 . Then we conclude that ζ_n is 1-Lipschitz with respect to the distance $\delta_{\rho_n * w}$. Relabelling the a_i 's as a list of positive and negative points $(p_j, n_j)_{j=1}^K$, we get from formula (1.6) and Theorem 1.1,

$$8\pi \sum_{j=1}^K \zeta_n(p_j) - \zeta_n(n_j) \leq E_{\rho_n * w}((a_i, d_i)_{i=1}^N).$$

Taking the lim inf as $n \rightarrow +\infty$, we obtain

$$8\pi \sum_{j=1}^K \zeta(p_j) - \zeta(n_j) \leq \liminf_{n \rightarrow +\infty} E_{\rho_n * w}((a_i, d_i)_{i=1}^N).$$

Since ζ is arbitrary, we deduce from (1.6) and Theorem 1.1 that

$$E_w((a_i, d_i)_{i=1}^N) \leq \liminf_{n \rightarrow +\infty} E_{\rho_n * w}((a_i, d_i)_{i=1}^N). \quad (4.4)$$

Since $\rho_n * w \leq \Lambda$, we obtain by dominated convergence that for any $u \in \mathcal{E}$,

$$\int_{\Omega} |\nabla u|^2 \rho_n * w(x) dx \xrightarrow{n \rightarrow +\infty} \int_{\Omega} |\nabla u|^2 w(x) dx$$

and therefore

$$\limsup_{n \rightarrow +\infty} E_{\rho_n * w}((a_i, d_i)_{i=1}^N) \leq \int_{\Omega} |\nabla u|^2 w(x) dx.$$

Since u is arbitrary, we infer that

$$\limsup_{n \rightarrow +\infty} E_{\rho_n * w}((a_i, d_i)_{i=1}^N) \leq E_w((a_i, d_i)_{i=1}^N), \quad (4.5)$$

and the result follows from (4.4) and (4.5).

Step 2: Assume that Ω is a smooth bounded and connected open set. We extend w by setting $w = M$ in $\mathbb{R}^3 \setminus \Omega$ for a large positive constant M that we will choose later. We fix some $\delta > 0$ small enough and consider

$$\Omega_\delta = \{x \in \mathbb{R}^3, \text{dist}(x, \Omega) < \delta\}.$$

We extend to Ω_δ any function ζ which is 1-Lipschitz with respect to d_w by setting $\zeta(x) = \zeta(\Pi x)$ for $x \in \Omega_\delta$ where Πx denotes the projection of $x \in \Omega_\delta$ on $\bar{\Omega}$. By construction, such a ζ is Lipschitz continuous on Ω_δ and $|\nabla \zeta| \leq C(\Omega, \delta, \Lambda)$ a.e. on $\Omega_\delta \setminus \Omega$ and $|\nabla \zeta| \leq w$ a.e. on Ω . Then we choose $M \geq C(\Omega, \delta, \Lambda)$. Setting $\zeta_n : x \in \Omega \rightarrow \rho_n * \zeta(x)$ for $n \geq 1/\delta$, we have $|\nabla \zeta_n| \leq \rho_n * w$ on Ω . Then ζ_n is 1-Lipschitz with respect to the distance $\delta_{\rho_n * w}$ and we can proceed as in Step 1. \blacksquare

Remark 4.2. If $(w_n)_{n \in \mathbb{N}}$ denotes the sequence constructed in Theorem 4.2, the previous results show that $d_{w_n} \rightarrow d_w$ uniformly on every compact subset of $\bar{\Omega} \times \bar{\Omega}$ and the functionals $\mathbb{L}_{d_{w_n}}$ Γ -converge to \mathbb{L}_{d_w} in $\text{Lip}([0, 1], \bar{\Omega})$.

5 Energy involving a Matrix Field

In this section, we consider $M = (m_{kl})_{k,l=1}^3$ a continuous map from $\bar{\Omega}$ onto the set of real symmetric 3×3 matrices such that

$$\lambda|\xi|^2 \leq M(x)\xi \cdot \xi \leq \Lambda|\xi|^2 \quad \text{for all } \xi \in \mathbb{R}^3 \text{ and } x \in \bar{\Omega}$$

(here “ \cdot ” denotes the Euclidean scalar product on \mathbb{R}^3) and we investigate on the problem

$$E_M((a_i, d_i)_{i=1}^N) = \inf_{u \in \mathcal{E}} \int_{\Omega} \sum_{k,l=1}^3 m_{kl}(x) \frac{\partial u}{\partial x_k} \cdot \frac{\partial u}{\partial x_l} dx.$$

Under the continuity assumption above, we show that $E_M((a_i, d_i)_{i=1}^N)$ can also be computed in terms of minimal connections relative to some geodesic distance on $\bar{\Omega}$.

In order to state the result we introduce the following objects. For $x \in \bar{\Omega}$, we denote by $\text{cof}(M(x))$ the cofactor matrix of $M(x)$. For any Lipschitz curve $\gamma : [0, 1] \rightarrow \bar{\Omega}$, we define the length $\mathbb{L}_M(\gamma)$ by

$$\mathbb{L}_M(\gamma) = \int_0^1 \sqrt{\text{cof}(M(\gamma(t))) \dot{\gamma}(t) \cdot \dot{\gamma}(t)} dt$$

and we construct from \mathbb{L}_M the Riemannian distance d_M on $\bar{\Omega}$ defined by

$$d_M(x, y) = \text{Inf } \mathbb{L}_M(\gamma)$$

where the infimum is taken over all curves $\gamma \in \text{Lip}_{x,y}([0, 1], \bar{\Omega})$.

Theorem 5.1. *We have*

$$E_M((a_i, d_i)_{i=1}^N) = 8\pi L_M$$

where L_M is the length of a minimal connection associated to the configuration $(a_i, d_i)_{i=1}^N$ and the distance d_M on $\bar{\Omega}$.

Remark 5.1. One can slightly relax the continuity assumption on M . For example, we can assume that

$$M(x) = \begin{cases} M_1(x) & \text{if } x \in \Omega_1, \\ M_2(x) & \text{if } x \in \Omega_2, \end{cases}$$

where Ω_1 and Ω_2 are two open sets of Ω with piecewise smooth boundaries such that $\bar{\Omega}_1 \cup \bar{\Omega}_2 = \bar{\Omega}$, and $x \rightarrow M_j(x)$ is continuous on $\bar{\Omega}_j$ for $j = 1, 2$. Hence M is possibly discontinuous on the surface $\Sigma = \bar{\Omega}_1 \cap \bar{\Omega}_2$. Then the conclusion of Theorem 5.1 holds with the geodesic distance d_M constructed from the length \mathbb{L}_M defined by

$$\mathbb{L}_M(\gamma) = \int_0^1 \varphi(\gamma(t), \dot{\gamma}(t)) dt \quad \text{for } \gamma \in \text{Lip}([0, 1], \bar{\Omega}),$$

where

$$\varphi(x, \nu) = \begin{cases} \sqrt{\text{cof}(M(x)) \nu \cdot \nu} & \text{if } x \in \bar{\Omega} \setminus \Sigma, \\ \min \left\{ \sqrt{\text{cof}(M_1(x)) \nu \cdot \nu}, \sqrt{\text{cof}(M_2(x)) \nu \cdot \nu} \right\} & \text{if } x \in \Sigma. \end{cases}$$

Open Problem . Assuming that the coefficients of M are only in $L^\infty(\Omega)$, is the conclusion of Theorem 5.1 still valid for a certain distance?

Sketch of the Proof of Theorem 3. The Lower Bound. We follow the strategy in Section 3. For any $u \in \mathcal{E}$, we have

$$2[\text{cof}(M)D \cdot D]^{1/2} \leq \sum_{k,l=1}^3 m_{kl}(x) \frac{\partial u}{\partial x_k} \cdot \frac{\partial u}{\partial x_l} \quad \text{a.e. on } \Omega \quad (5.1)$$

where D is the vector field defined by (3.1). Next we infer that

$$\int_{\Omega} \sum_{k,l=1}^3 m_{kl}(x) \frac{\partial u}{\partial x_k} \cdot \frac{\partial u}{\partial x_l} dx \geq -2 \int_{\Omega} D \cdot \nabla \zeta = 8\pi \sum_{j=1}^K \zeta(p_j) - \zeta(n_j) \quad (5.2)$$

for any Lipschitz function $\zeta : \bar{\Omega} \rightarrow \mathbb{R}$ such that

$$[\text{cof}(M)^{-1} \nabla \zeta \cdot \nabla \zeta]^{1/2} \leq 1 \quad \text{a.e. in } \Omega. \quad (5.3)$$

Since a function ζ satisfies (5.3) if and only if ζ is 1-Lipschitz with respect to the distance d_M , we conclude from (5.2) that

$$E_M((a_i, d_i)_{i=1}^N) \geq 8\pi \text{Max} \sum_{j=1}^K \zeta(p_j) - \zeta(n_j) = 8\pi L_M$$

where the maximum is taken over all functions ζ which is 1-Lipschitz with respect to the distance d_M .

The Upper Bound. The proof relies on the dipole construction.

Lemma 5.1. *For any distinct points $P, N \in \Omega$, any smooth simple curve $\gamma \subset \Omega$ running between P and N and $\delta > 0$, there exists a map u_{δ} in $\mathcal{C}_{\text{loc}}^1(\bar{\Omega} \setminus \{P, N\}, S^2)$ such that $\deg(u_{\delta}, P) = +1$, $\deg(u_{\delta}, N) = -1$ and*

$$\int_{\Omega} \sum_{k,l=1}^3 m_{kl}(x) \frac{\partial u_{\delta}}{\partial x_k} \cdot \frac{\partial u_{\delta}}{\partial x_l} dx \leq 8\pi \mathbb{L}_M(P, N) + \delta. \quad (5.4)$$

Moreover u_{δ} is constant outside an arbitrary small neighborhood of γ .

We may assume that $\sum_j d_M(p_j, n_j) = L_M$. Then we choose K smooth simple curves γ_j running between p_j and n_j which do not intersect except at their endpoints and such that $\mathbb{L}_M(p_j, n_j) \leq d_M(p_j, n_j) + \delta$. By Lemma 5.1, we construct K maps u_j constant outside a small neighborhood \mathcal{N}_j of γ_j and $\mathcal{N}_j \cap \mathcal{N}_i = \emptyset$ if $j \neq i$. Letting $u_{\delta} = u_j$ on \mathcal{N}_j for $j = 1, \dots, K$ and $u_{\delta} = (0, 0, 1)$ outside $\cup_j \mathcal{N}_j$, we have $u_{\delta} \in \mathcal{E}$ and

$$E_M((a_i, d_i)_{i=1}^N) \leq \int_{\Omega} \sum_{k,l=1}^3 m_{kl}(x) \frac{\partial u_{\delta}}{\partial x_k} \cdot \frac{\partial u_{\delta}}{\partial x_l} dx \leq 8\pi L_M + C\delta.$$

Since δ is arbitrary, we obtain that $E_M((a_i, d_i)_{i=1}^N) \leq 8\pi L_M$. ■

Sketch of the Proof of Lemma 5.1. Since we can approximate the coefficients of M locally uniformly by smooth coefficients, we just have to prove Lemma

5.1 for M with smooth entries. We construct as in [1] a smooth diffeomorphism Φ from a small neighborhood \mathcal{V} of γ into a small neighborhood of $\{(0, 0)\} \times [-|\gamma|/2, |\gamma|/2]$ such that $\Phi(\gamma) = \{(0, 0)\} \times [-|\gamma|/2, |\gamma|/2]$ (here $|\gamma|$ denotes the Euclidean length of γ) and $\Phi^{-1}(0, 0, \cdot) : [-|\gamma|/2, |\gamma|/2] \rightarrow \mathbb{R}^3$ defines a normal parametrization of γ orientating γ from N to P . Then we set for $y_3 \in [-|\gamma|/2, |\gamma|/2]$,

$$B(y_3) = (b_{k,l}(y_3))_{k,l=1}^3 = [\nabla \Phi^{-1}(0, 0, y_3)]^{-1} M(\Phi^{-1}(0, 0, y_3)) \nabla \Phi^{-1}(0, 0, y_3),$$

and

$$\hat{B}(y_3) = (b_{k,l}(y_3))_{k,l=1}^2.$$

For small $\varepsilon > 0$ and $n \in \mathbb{N}$ large, we consider the map $\tilde{u}_n : \Phi(\mathcal{V}) \rightarrow S^2$ defined by

$$\tilde{u}_n(y_1, y_2, y_3) = \omega_\varepsilon \left(\frac{n}{\frac{|\gamma|^2}{4} - y_3^2} \hat{B}^{-1/2}(y_3) \cdot (y_1, y_2) \right)$$

where ω_ε is given by (3.5). Then we take

$$u_n(x) = \begin{cases} \tilde{u}_n(\Phi(x)) & \text{if } x \in \mathcal{V}, \\ (0, 0, 1) & \text{if } x \notin \mathcal{V}. \end{cases}$$

Following the computations in [6] and using the properties of Φ , we check that $u_n \in W_{\text{loc}}^{1,\infty}(\bar{\Omega} \setminus \{P, N\}, S^2)$, $\deg(u_n, P) = +1$, $\deg(u_n, N) = -1$. Choosing n sufficiently large and smoothening u_n around γ by the procedure in [2], we get a new map $u_\delta \in \mathcal{E}$ which satisfies (5.4). \blacksquare

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