

x20

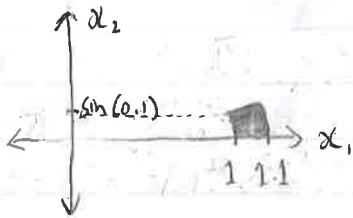
Hw 3

1. $f(x+\Delta x, y+\Delta y) = (x^2 + 2x\Delta x + \Delta x^2)(y^2 + 2y\Delta y + \Delta y^2)$
 $= x^2y^2 + 2x^2y\Delta y + x^2\Delta y^2 + 2xy^2\Delta x + 4xy\Delta x\Delta y + 2x\Delta x\Delta y^2 + y^2\Delta x^2 + 2y\Delta x^2\Delta y + \Delta x^2\Delta y^2$
 $= f(x,y) + 2xy^2\Delta x + 2x^2y\Delta y + (x^2\Delta y)\Delta y + (4xy\Delta y + 2x\Delta y^2 + y^2\Delta x + 2y\Delta x\Delta y + \Delta x\Delta y^2)\Delta x$

$\lim_{(\Delta x, \Delta y) \rightarrow (0,0)} \epsilon_1(x,y,\Delta x,\Delta y) = 0$ by continuity of $+$, $*$
 $\lim_{(\Delta x, \Delta y) \rightarrow (0,0)} \epsilon_2(x,y,\Delta x,\Delta y) = 0$ by continuity of $+$, $*$

$\therefore a(x,y) = 2xy^2, b(x,y) = 2x^2y,$
 $\epsilon_1(x,y,\Delta x,\Delta y) = (4xy\Delta y + \dots + x\Delta y^2), \epsilon_2(x,y,\Delta x,\Delta y) = x^2\Delta y$

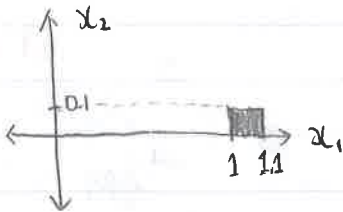
2. a.)



The area is $\frac{0.1}{2} \cdot (1 \cdot 1^2 - 1) = 0.0105$

b.) $\begin{bmatrix} \partial f_1 / \partial x_1 & \partial f_1 / \partial x_2 \\ \partial f_2 / \partial x_1 & \partial f_2 / \partial x_2 \end{bmatrix} = \begin{bmatrix} \cos(x_2) & -x_1 \sin(x_2) \\ \sin(x_2) & x_1 \cos(x_2) \end{bmatrix} = J(x_1, x_2)$

c.)



$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} \Delta x_1 \\ \Delta x_2 \end{bmatrix} = \begin{bmatrix} \Delta x_1 \\ \Delta x_2 \end{bmatrix}$
 The area is $0.1 \cdot 0.1 = 0.01$

3. a.) $z|_{t=1} = f(0,1) \quad z|_{t=0} = f(1,0)$

Use chain rule b/c total differentiability

$\frac{\partial z}{\partial t} |_{t=1} = \frac{\partial f}{\partial x}(0,1) \cdot \frac{\partial}{\partial t}(1-t^2)|_{t=1} + \frac{\partial f}{\partial y}(0,1) \cdot \frac{\partial}{\partial t}(t^3)|_{t=1}$
 $= 8 \cdot (-2) + 9 \cdot (3) = 11$

$\frac{\partial z}{\partial t} |_{t=0} = \frac{\partial f}{\partial x}(1,0) \cdot \frac{\partial}{\partial t}(1-t^2)|_{t=0} + \frac{\partial f}{\partial y}(1,0) \cdot \frac{\partial}{\partial t}(t^3)|_{t=0}$
 $= 0$ (the $\frac{\partial}{\partial t}$ terms = 0)

4. $r \cos \theta$ and $r \sin \theta$ are totally differentiable at all (r, θ)

+4

$$\begin{aligned} \frac{\partial z}{\partial r} &= \frac{\partial z}{\partial x} \cdot \frac{\partial x}{\partial r} + \frac{\partial z}{\partial y} \cdot \frac{\partial y}{\partial r} \\ &= \frac{\partial z}{\partial x} \cdot (\cos \theta) + \frac{\partial z}{\partial y} \cdot (\sin \theta) \\ \frac{\partial z}{\partial \theta} &= \frac{\partial z}{\partial x} \cdot \frac{\partial x}{\partial \theta} + \frac{\partial z}{\partial y} \cdot \frac{\partial y}{\partial \theta} \\ &= \frac{\partial z}{\partial x} \cdot (-r \sin \theta) + \frac{\partial z}{\partial y} \cdot (r \cos \theta) \\ &= r \cdot \left(-\frac{\partial z}{\partial x} \sin \theta + \frac{\partial z}{\partial y} \cos \theta \right) \\ \left(\frac{\partial z}{\partial r} \right)^2 + \frac{1}{r^2} \left(\frac{\partial z}{\partial \theta} \right)^2 &= \left(\frac{\partial z}{\partial x} \right)^2 (\cos^2 \theta + \sin^2 \theta) + \left(\frac{\partial z}{\partial y} \right)^2 (\sin^2 \theta + \cos^2 \theta) \\ &= \left(\frac{\partial z}{\partial x} \right)^2 + \left(\frac{\partial z}{\partial y} \right)^2 \end{aligned}$$

5. a.) $\vec{y}_x = \begin{bmatrix} \frac{\partial f_1}{\partial x_1} & \frac{\partial f_1}{\partial x_2} \\ \frac{\partial f_2}{\partial x_1} & \frac{\partial f_2}{\partial x_2} \end{bmatrix} = \begin{bmatrix} 2x_1 & -2x_2 \\ 2x_2 & 2x_1 \end{bmatrix}$ ✓

+6 $\frac{\partial (y_1, y_2)}{\partial (x_1, x_2)} = 4x_1^2 + 4x_2^2$ ✓

b.) $\begin{cases} y_1 = x_1^2 - x_2^2 \\ y_2 = 2x_1 x_2 \end{cases} \Rightarrow \begin{cases} 2x_1 \frac{\partial x_1}{\partial y_1} - 2x_2 \frac{\partial x_2}{\partial y_1} = 1 \\ 2x_2 \frac{\partial x_1}{\partial y_1} + 2x_1 \frac{\partial x_2}{\partial y_1} = 0 \end{cases}$

$\Rightarrow \begin{cases} x_1 x_2 \frac{\partial x_1}{\partial y_1} - x_2^2 \frac{\partial x_2}{\partial y_1} = x_2/2 \\ x_1 x_2 \frac{\partial x_1}{\partial y_1} + x_1^2 \frac{\partial x_2}{\partial y_1} = 0 \end{cases}$

$\Rightarrow \begin{cases} x_1 \frac{\partial x_1}{\partial y_1} - x_2 \frac{\partial x_2}{\partial y_1} = 1/2 \\ (x_1^2 + x_2^2) \frac{\partial x_2}{\partial y_1} = -x_2/2 \end{cases}$

$\Rightarrow \begin{cases} \frac{\partial x_2}{\partial y_1} = -x_2 / 2(x_1^2 + x_2^2) \\ x_1 \frac{\partial x_1}{\partial y_1} + x_2 \frac{\partial x_2}{\partial y_1} = 1/2 \end{cases} \Rightarrow \begin{cases} \frac{\partial x_1}{\partial y_1} = \frac{x_1}{2(x_1^2 + x_2^2)} \\ \frac{\partial x_2}{\partial y_1} = \frac{x_2}{2(x_1^2 + x_2^2)} \end{cases}$ ✓

$\begin{cases} y_1 = x_1^2 - x_2^2 \\ y_2 = 2x_1 x_2 \end{cases} \Rightarrow \begin{cases} 2x_1 \frac{\partial x_1}{\partial y_2} - 2x_2 \frac{\partial x_2}{\partial y_2} = 0 \\ 2x_2 \frac{\partial x_1}{\partial y_2} + 2x_1 \frac{\partial x_2}{\partial y_2} = 1 \end{cases}$

$\Rightarrow \begin{cases} x_1 \frac{\partial x_1}{\partial y_2} - x_2 \frac{\partial x_2}{\partial y_2} = 0 \\ (x_1^2 + x_2^2) \frac{\partial x_2}{\partial y_2} = x_1/2 \end{cases}$ ✓

$\Rightarrow \begin{cases} \frac{\partial x_2}{\partial y_2} = \frac{x_1}{2(x_1^2 + x_2^2)} \\ x_1 \frac{\partial x_1}{\partial y_2} - x_1 x_2 / 2(x_1^2 + x_2^2) = 0 \end{cases} \Rightarrow \begin{cases} \frac{\partial x_1}{\partial y_2} = \frac{x_2}{2(x_1^2 + x_2^2)} \\ \frac{\partial x_2}{\partial y_2} = \frac{x_1}{2(x_1^2 + x_2^2)} \end{cases}$ ✓

$$\vec{J}_{\vec{y}} = \begin{bmatrix} \partial x_1 / \partial y_1 & \partial x_1 / \partial y_2 \\ \partial x_2 / \partial y_1 & \partial x_2 / \partial y_2 \end{bmatrix} = \begin{bmatrix} x_1 & x_2 \\ -x_2 & x_1 \end{bmatrix} \cdot \frac{1}{2(x_1^2 + x_2^2)}$$

$$\partial(x_1, x_2) / \partial(y_1, y_2) = \frac{1}{4(x_1^2 + x_2^2)^2} \cdot (x_1^2 + x_2^2) = \frac{1}{4(x_1^2 + x_2^2)} \quad \checkmark$$

$$c.) \begin{bmatrix} x_1 & -x_2 \\ x_2 & x_1 \end{bmatrix} \cdot \begin{bmatrix} x_1 & x_2 \\ -x_2 & x_1 \end{bmatrix} : 2 \cdot \frac{1}{2(x_1^2 + x_2^2)}$$

$$= \begin{bmatrix} x_1^2 + x_2^2 & 0 \\ 0 & x_2^2 + x_1^2 \end{bmatrix} \cdot \frac{1}{(x_1^2 + x_2^2)} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \quad \checkmark$$

$$\det(\vec{J}_{\vec{x}}) \cdot \det(\vec{J}_{\vec{y}}) = 4(x_1^2 + x_2^2) \cdot \frac{1}{4(x_1^2 + x_2^2)} = 1$$

6. F is continuous because it is composed from the sums of products of continuous functions $x, y, \cos(y), -1, \sin(y), 2$

$\times b$ $\partial F / \partial x = 2x$ is continuous (same reason)

$\partial F / \partial y = 2y + \sin(y)$ is continuous

a.) $\partial F / \partial x(1, 0) = 2 \neq 0$. So the conditions for the implicit function theorem are satisfied.

b.) $\partial F / \partial y(1, 0) = 0 + 0 = 0$, which is prohibited. So the conditions are not satisfied.

c.) Consider $d/dx F(x, Y(x))$ at $x=1$:

On the one hand, since there is an open region around $x=1$ where Y is defined and $F(x, Y(x)) = 0$,

$\exists d > 0$ s.t. Y is defined for $x \in (1-d, 1+d)$. Fix d .

So $F(x, Y(x)) = 0$ for all $x \in (1-d, 1+d) = U$.

$$\begin{aligned} d/dx F(x, Y(x)) \Big|_{x=1} &= \lim_{\Delta x \rightarrow 0} \frac{F(1+\Delta x, Y(1+\Delta x)) - F(1, Y(1))}{\Delta x} \\ &= 0 \quad \text{within the restricted domain} \end{aligned}$$

On the other hand... $d/dx F(x, Y(x)) \Big|_{x=1} = \frac{\partial F}{\partial x}(1, 0) \frac{\partial x}{\partial x} + \frac{\partial F}{\partial y}(1, 0) \frac{\partial Y}{\partial x}$ ← differential Y assumption.

$$= \frac{\partial F}{\partial x}(1, 0) + 0 \cdot \frac{\partial Y}{\partial x} = 0.$$

$$\Rightarrow \frac{\partial F}{\partial x} \Big|_{x=1} = 0 \quad \Rightarrow 2 = 0 \quad \times$$

A differentiable Y containing $Y(1) = 0$ and
 $F(x, Y(x)) = 0$ in an open region near $x=1$
cannot exist